

for a greener tomorrow

MELSEC iQ-F Series iQ Platform-compatible PLC

# The next level of industry









# MELSEC 1Q-Fesseries

Designed on the concepts of outstanding performance, superior drive control and user centric programming, Mitsubishi's MELSEC-F Series has been reborn as the MELSEC iQ-F Series.

From stand alone use to networked system applications, MELSEC iQ-F Series brings your business to the next level of industry.



# The next level of industry

The newly reborn MELSEC iQ-F Series reaches to new areas of application with a high-speed system bus, extensive built-in functions and network support.









Conveyance

Food & Beverage

Packaging

Air-conditioning

### New micro PLC designed on the concepts of ...



- High-speed system bus
- Extensive built-in functions
- Enhanced security functions
- Battery-less



- Easy built-in positioning (4-axis 200 Kpps)
- Simple interpolation functions
- 4-axis synchronous control with Simple Motion module (dedicated positioning software not needed)



- Easy programming by drag and drop
- Reduced development time with module FB
- Parameterized setup for a variety of functions



GX Works3





# Taking the iQ Platform to the next level.

iQ platform minimizes TCO\* by providing innovative solutions for:

- Building a stable production system with enhanced productivity
- Reducing the time from system development to startup for shorter product cycles
- Efficiently managing and servicing the system to reduce down time and maintain productivity
- Ensuring product quality by swiftly processing enormous volumes of control data and production data and establishing traceability

\* TCO: Total Cost of Ownership

### **PLC & HMI**

- 1. MELSEC iQ-F Series greatly enhances the total system performance with the high-speed system bus performance ( $150 \times$  conventional speed \*1)
- 2. Standardize programs with dedicated memory for function blocks and module labels
- 3. Uniform and powerful security functions

### **Network**

- Achieve loss-less retrieval with CC-Link IE Field (future support)
   Gbps high-speed communication (link refresh performance 40× conventional levels \*1)
- 2. Seamless connectivity with each device using SLMP\* (future support)

  \*SLMP: SeamLess Message Protocol

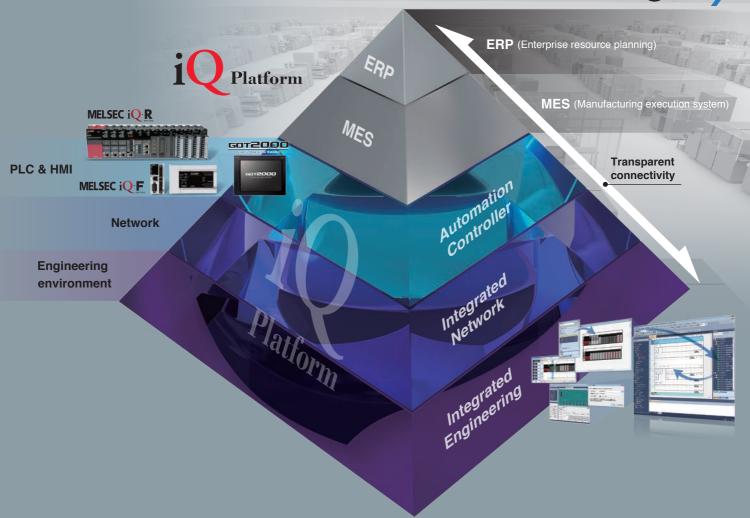
# **Engineering Environment**

- 1. Detect and automatically generate network configuration diagrams from actual machines (future support)
- 2. Share parameters across multiple engineering software via MELSOFT Navigator (future support)











# **Advanced Built-in Functions**

### **CPU Performance**

A new sequence execution engine is at the core of MELSEC iQ-F, capable of running structured programs and multiple programs, and supports structured text and function blocks, etc.

64 k steps

**14.6** nstructions/με

minimum 1 ms

### **Built-in Analog Input/Output**

(with alarm output) FX5U

FX5U is equipped with 12-bit 2ch analog input and 1ch analog output. With parameter setup, no programming is required.

Value shifting, scaling and alarm output can also be set easily with parameters.

» Example of inverter control with analog output

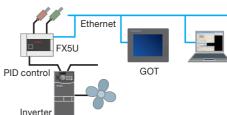
FXS-485ADP

PWRD

RD:

FX5-232ADP

RD\* SD .

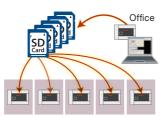


### **Built-in SD Card Slot**

A built-in SD card slot is convenient for updating the program and mass production of equipment.

Data can be logged in SD card (future support), making it easy to analyze the system status and production state, etc.

» Example of mass production of equipment using SD card



Production site

### RUN/STOP/RESET Switch

The RUN/STOP switch now includes RESET function. PLC can be rebooted without turning off the main power for efficient debugging.

# FX5U

MELSEC

SD SD/RD

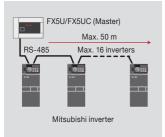
OBASE-T/100BASE-TX

### Space saving

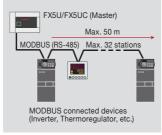
# **Built-in RS-485 Port (with MODBUS® function)**

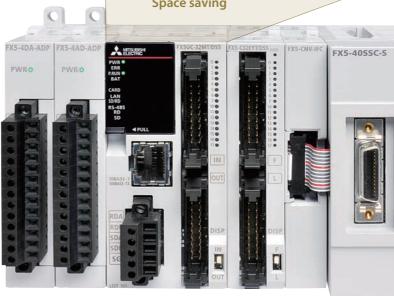
Connect to serial devices up to 50 m away with built-in RS-485 port. Control for up to 16 Mitsubishi inverters is possible with dedicated inverter communication instructions. The MODBUS function supports a connection of up to 32 peripheral units including PLCs, sensors and thermoregulators.

### » Inverter Communication



### » MODBUS Communication









### **Security**

POWER O RUN O ERROR •

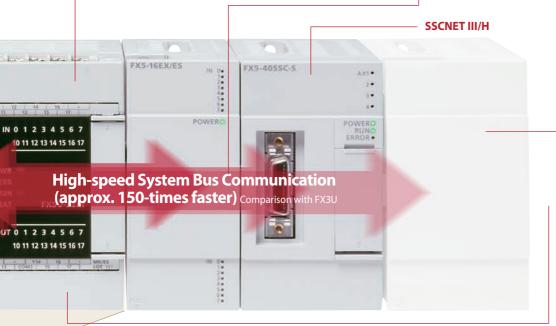
MELSEC iQ-F has advanced security functions (file password, remote password, security key) to prevent data theft and illegal operations by unauthorized persons.

### » Example of Security key function



### **High-speed System Bus** Communication

MELSEC iQ-F realizes high-speed system bus communication at speeds of 1.5 k words/ms (approx. 150-times faster than FX3U). Achieve maximum performance even when using intelligent function module with large amounts of data.



**CC-Link IE Field** 



### **Battery-less and** Maintenance-free

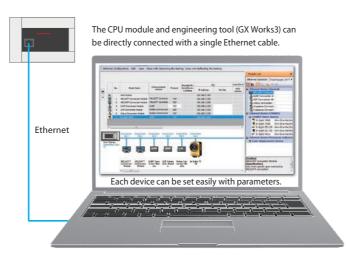
Programs can be saved even without a battery, and clock data can be saved for ten days by supercapacitor.

(May vary by usage state)

\*: Clock data and device memory can be saved (latched) during a power outage by using the optional battery.

### **Built-in Ethernet Port**

The Ethernet communication port can handle communication of up to 8 connections on the network, and can support multiple connections with personal computer and other device. This port also supports remote maintenance and other seamless SLMP communication with host devices.



### » Socket Communication

Directly connect to other PLCs.



### » Remote Maintenance

Program read/write can be made by GX Works3 connected via VPN.



### » SLMP Communication

Device data read-out/writing to PLC from external device is possible.

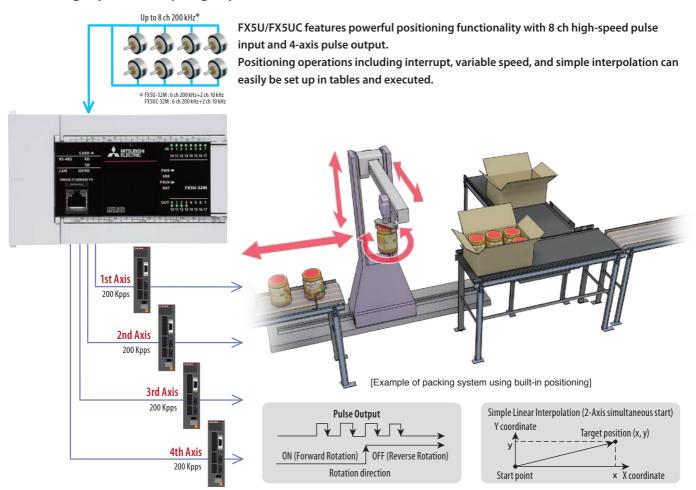


» MODBUS/TCP client

# **Advanced positioning function**

# Built-in Positioning (200 Kpps, 4-Axis built-in)

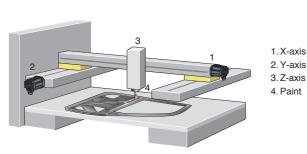
Positioning capable of 20 µs high-speed start



# Simple Motion Module <4-Axis control module>

### Positioning control with SSCNET III/H

FX5-40SSC-S is equipped with a 4-axis positioning function compatible with SSCNET III/H. By combining linear interpolation, 2-axis circular interpolation and continuous trajectory control in the program set with a table, a smooth trajectory can be easily drawn.



[Example of sealing system]

### Main functions

- · Linear interpolation
- · Circular interpolation
- Continuous trajectory control

### S-curve acceleration/deceleration

### Application examples

FX5-40SSC-S SSCNETIII/H

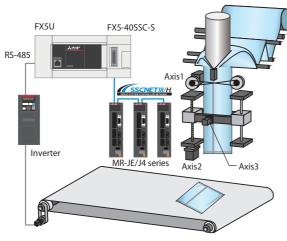
- Sealing system
- · Automatic vending machines
- Palletizer
- Grinding system



# **Advanced Motion Control**

### Making Simple Motion with compactly packed extra functions

By starting with parameter settings and the sequence program, the Simple Motion modules can realize a variety of motion control including positioning control, advanced synchronous control, cam control and speed-torque control.



[Example of packaging machine using Simple Motion]

- Use synchronous control and cam control to build a system perfect for your equipment.
- Register up to 64 types of cam patterns to respond to any type of packaging needs.
- Perform continuous operation without stopping the workpiece operation.

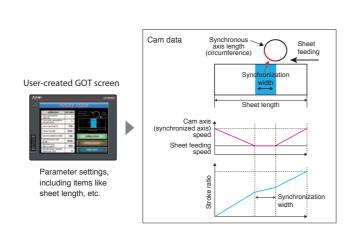
### **Synchronous control**

In addition to synchronous control that replaces physical machine mechanisms such as gears, shaft, transmission and cam with software, functions such as cam control, clutch and cam auto-generation are easily realized. Since synchronous control can be started and stopped for each axis, programs can contain both synchronous control axes and positioning control axes.

Up to four axes can be synchronized to the synchronous encoder axis, enabling use with a variety of systems.

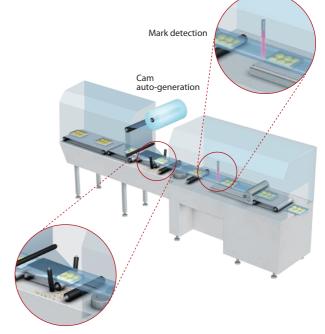
### Cam data auto-generation

Easily program and automatically generate difficult cam data for rotary cutters just by inputting the sheet length, synchronization width, and cam resolution, etc.



### Mark detection function

The cutter axis deviation can be compensated by detecting a mark on the workpiece so the workpiece can be cut at a constant position.



[Example of rotary cutter control with mark detection and cam data]

# **User-friendly programming software**



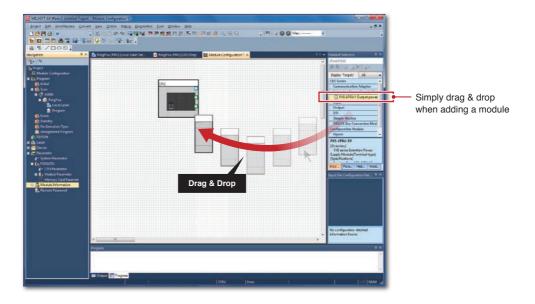
Software that comprehensively supports programming and maintenance streamlines operations.

Easily and intuitively program by making "selections" in a graphical environment.

Reduce maintenance and engineering costs with diagnosis and troubleshooting function.

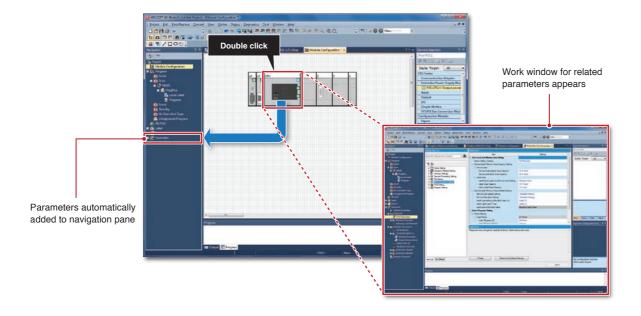
### System design with a convenient parts library

With GX Works3, designing a system is as easy as preparing the module configuration diagram by dragging and dropping selected parts.



### **Auto-generation of module parameters**

When preparing the module configuration diagram, simply double-click the module to automatically generate the module parameters. A window with an easy-to-use parameter settings screen opens, enabling module parameters to be modified as needed.

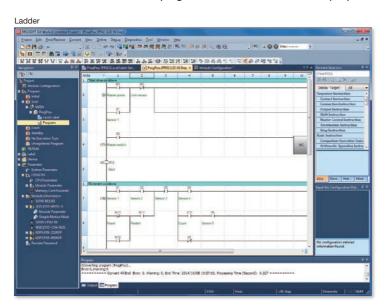


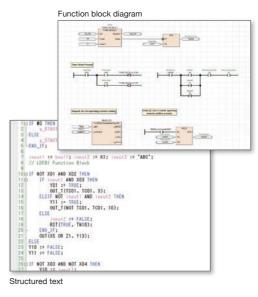


### Main programming languages supported

The main IEC languages are supported by GX Works3. Various different programming languages can be used within the same project simultaneously and can be viewed easily via the menu tab.

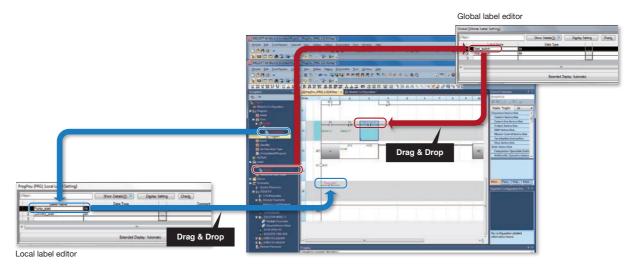
The labels and devices used in each program can be shared across multiple platforms, with user defined function blocks supported.





Reduce repetitive program tasks

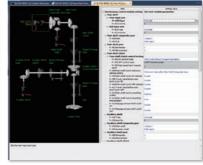
Global labels, local labels and module labels are supported by GX Works3. Global labels can be shared by multiple programs and with other MELSOFT software. Local labels can be used in registered programs and function blocks. Module labels contain buffer memory information for various intelligent function modules and eliminates the need to reference buffer memory address.

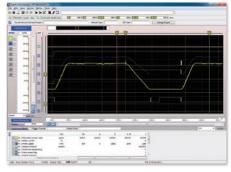


### **Integrated motion setup tool**

GX Works3 is equipped with a special motion setup tool that makes it easy to change simple motion module settings such as module parameters, positioning data and servo parameters. Also, the servo adjustment is simplified using it.







System configuration

Synchronous control parameter

Digital oscilloscope

# **Advanced MELSEC iQ-F Series**

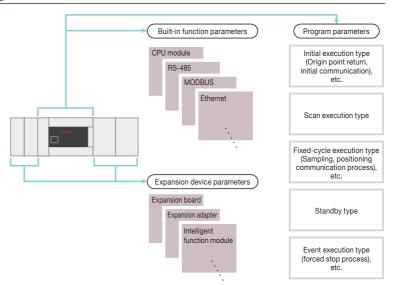
### Simple and convenient parameter settings

With MELSEQ iQ-F, various device settings that conventionally had to be programmed can be input in table format.

Easily set the built-in functions as well as expansion devices just by inputting values into the parameters. The program's execution trigger can also be set with the parameters.

### [Functions set with parameters]

- Settings for CPU parameters, Ethernet port, RS-485 communication port, input response time, expansion board, memory card, security, etc.
- Settings for expansion adapters and intelligent function module



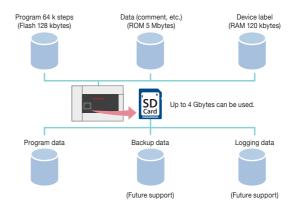
### Memory area for each application

The CPU module has 64 k steps of program memory capacity, but the MELSEC iQ-F has a memory data area for each application, so all 64 k steps can be used as the program area.

Comments and statements can be written freely without affecting the program area.

# [Maximum number of characters] Comment: 1024 characters Statement: 5000 characters

MELSEC IQ-F Series stores the program and devices in non-volatile memory such as Flash ROM, so no battery is required.



### Flexible internal devices

A variety of devices including new latch relays and link relays, and expanded timers and counters are available. The number of device points can be reassigned and used in the internal memory.

### Providing the convenience of special devices

In addition to the conventional special devices, up to 12000 points of convenient system devices compatible with high-end devices can be added.

# New high-end compatible system devices

• SM/SD 0 to 4099 Compatible with MELSEC iQ-R



### Conventional convenient devices

- Conventional M8000 devices
  - → Has changed to SM8000 devices
- Conventional D8000 devices
- → Has changed to SD8000 devices (When migrating an FX3U/FX3UC program created using GX Works2 to FX5, the devices are automatically converted.)

### Freely customize the latch range setting

The latch range can be set for each device, so the latch clear range can be selected during the clearing operation.



### Handy timer and counter settings

The timer and counter properties are determined by data type and how instruction is written, so programs can be created regardless of the device number.

### Timers:

OUT T0.......100 ms timer OUTH T0......10 ms timer OUTHS T0....1 ms timer OUT ST0 ..... Retentive timer

### Counters:

OUT C0......16 bit counter OUT LC0......32 bit counter

# **Software**

### **Dramatically more dedicated instructions**

A great number of dedicated instructions have been added since the FX3 Series.

[FX3] 510 types increased to [FX5] 1014 types

The newly added instructions include convenient ones that are interchangeable with the MELSEC iQ-R and dedicated instructions for built-in functions.

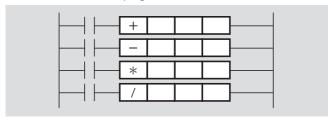


MELSEC iQ R

(Programs created with GX Works2 can also be read in and converted.)

### Intuitive and easy-to-understand arithmetic operations

Symbols can be input in the arithmetic operations making it easy and intuitive to describe programs.



### High-performance built-in high-speed counter function

Input and measure three modes by setting the parameters.

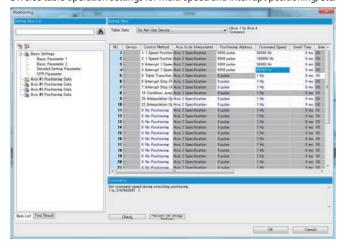
Normal mode
 Pulse density
 measurement mode
 Rotation speed
 measurement mode

Up to four tables can be set for the high-speed comparison table and up to 128 tables for the multi-point output high-speed comparison table. The HCMOV instruction can be used to read the latest values from the special registers.

### **Reinforced built-in positioning function**

Positioning is easy using table operations. Simple linear interpolation operation is possible by using the positioning instruction DRVTBL with multiple table operation and the multiple axis simultaneous drive positioning instruction DRVMUL.

Diverse table operation settings for multi-speed and interrupt positioning, etc.



### **Inverter communication command function**

The built-in Mitsubishi inverter protocol makes it possible to use inverter communication instructions to control a Mitsubishi inverter connected with RS-485 communication.

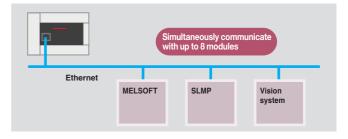
• IVCK : Operation monitor
• IVDR : Operation control
• IVRD : Parameter read
• IVWR : Parameter write
• IVBWR : Parameter batch write
• IVMC : Multiple command
(2 types of settings and 2 types of read)

\*: For built-in RS-485 communication

### **Built-in Ethernet function**

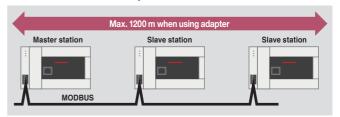
Communication is set with parameters and programs are made with dedicated instructions.

Functions including the diagnosis function from GX Works3, SLMP function, socket communication function and IP address change function and unauthorized access from an external source can be prevented with remote password.



### **MODBUS function**

The MODBUS function can be used with parameter settings and ADPRW (MODBUS master communication instruction [data read/write.]) Communicate with devices up to 1200 m away using the RS-485 communication adapter.



### Standard function/function block function

110 types of basic standard function and function blocks are provided. These can be used as parts by dragging and dropping, so when used together with dedicated instructions, programming time can be greatly reduced.



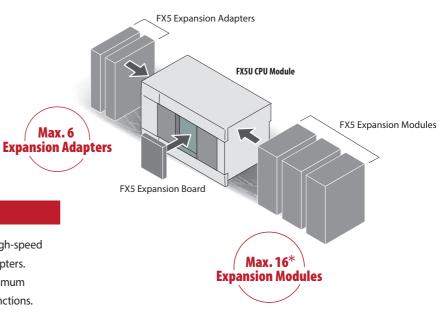
# **System Configuration**



Flagship model equipped with advanced built-in functions and diverse expandability

### Simplifying use with renewed expansion modules!

FX5U is equipped with analog functions, communication and high-speed I/O, and can easily be expanded with expansion boards and adapters. The high-speed system bus communication brings out the maximum performance of expansion devices equipped with intelligent functions.



 $\star$ : Excluding extension power supply module

### **FX5 Expansion Adapters**







### **FX5U CPU Modules**

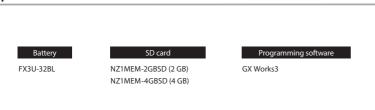






T2 Transistor output (source)

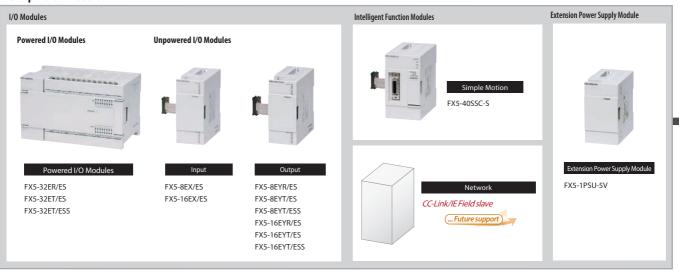


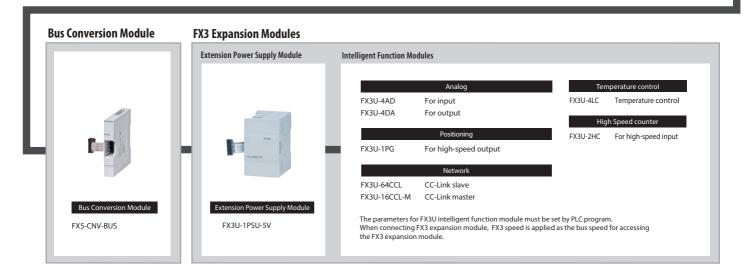


**Generic Specifications** 

	Item	Generic Specifications
Power supply, input/output	Power supply specifications	100 to 240 V AC 50/60 Hz
	Power consumption	30 W (32M), 40 W (64M), 45 W (80M)
	Rush current	FX5U-32M[]: max. 25 A 5 ms or less/100 V AC, max. 50 A 5 ms or less/200 V AC
		FX5U-64M[]/FX5U-80M[]: max. 30 A 5 ms or less/100 V AC, max. 60 A 5 ms or less/200 V AC
	5 V DC power supply capacity	900 mA or less (32M), 1100 mA or less (64M, 80M)
	24 V DC power supply capacity	
		When using external power supply for CPU module input: 480 mA or less (32M), 740 mA or less (64M), 770 mA or less (80M)
	Input specifications	24 V DC, 5.3 mA (X020 and above: 4 mA)
	Output specifications	Relay output type: 2 A/1 point, 8 A/4 points common, 8 A/8 points common 250 V AC (240 V for CE, UL/cUL Standard compliance), 30 V DC or less Transistor output type: 0.5 A/1 point, 0.8 A/4 points, 1.6 A/8 points common 5 to 30 V DC
	Input/output expansion	Expansion device for FX5 can be connected
Built-in communication port		Ethernet (100BASE-TX/10BASE-T), RS-485 (MELSOFT connection, MC protocol, non-protocol communication, MODBUS RTU, inverter communication, N:N communication)
Built-in memory card slot		1 slot for SD memory card
Built-in analog input/output		Input 2 ch, output 1 ch

### **FX5 Expansion Modules**







FX5 Expansion Adapters

FX5UC CPU Module

FX5 Expansion Modules (connector type)

Connector Conversion Modules (terminal block type)

wnsizing!

easy-to-use,

FX5 Expansion Modules

Expansion Adapters

FX5 Expansion Modules

Expansion Modules

Compact body packed with diverse functions.

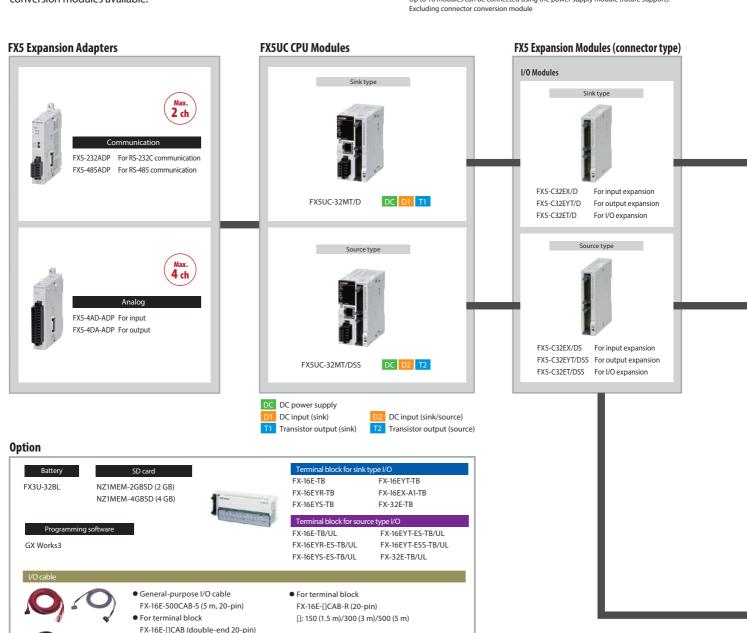
### Compact expansion module contributes to system downsizing!

The expansion module compatible with FX5UC is compact and easy-to-use, and helps to downsize your system.

[]: 150 (1.5 m)/300 (3 m)/500 (5 m)

Easily connect to the FX5 and FX3 expansion modules with the variety of conversion modules available.

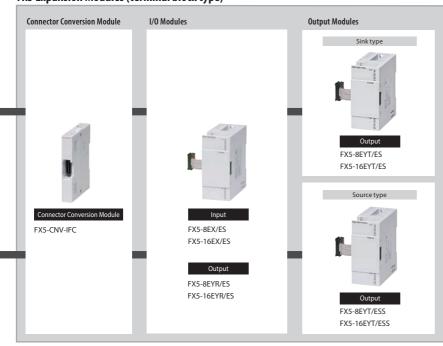
\*: Due to power limitations, only 12 modules can be directly connected to the CPU module. Up to 16 modules can be connected using the power supply module (future support).

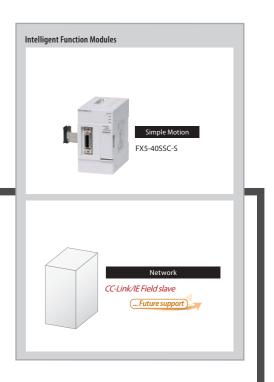


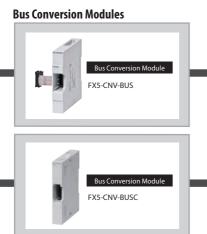
### **Generic Specifications**

	Item	Generic specifications
Power supply, Input/output	Power supply specifications	24 V DC
	Power consumption	8 W (32M)
	Rush current	Max. 30 A 0.5 ms or less/24 V DC
	5 V DC power supply capacity	720 mA or less (32M)
	24 V DC power supply capacity	500 mA or less (32M)
	Input specifications	24 V DC, 5.3 mA
	Output specifications	Transistor output type: Y000 to Y003 0.3 A/1 point, Y004 and higher 0.1 A/1 point, 0.8 A/8 points common 5 to 30 V DC
	Input/output expansion	Expansion device for FX5UC and FX5 (connector adapter required) can be connected
Built-in communication port		Ethernet (100BASE-TX/10BASE-T),
		RS-485 (MELSOFT connection, MC protocol, non-protocol communication, MODBUS RTU, inverter communication, N:N communication)
Built-in memory card slot		1 slot for SD memory card

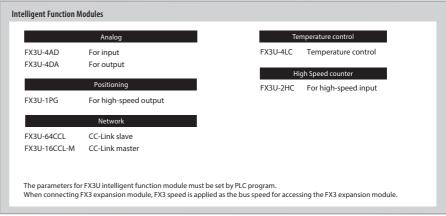
### FX5 Expansion Modules (terminal block type)







### **FX3 Expansion Modules**



# **Selecting the FX5U Model**

### **■**Product configuration



Туре	Details	Connection details, model selection
1 CPU module	PLC with built-in CPU, power supply, input/output and program memory.	Various expansion devices can be connected.
2 4 I/O module	Product for expanding I/O. Some products are powered.	Input/output can be expanded to up to 256 points. (Expansion module: Max. 16 modules (excluding extension power supply module)). The total with CC-Link remote input/output is max. 512 points.
3 FX5 extension power supply module	Module for expanding power supply if CPU module's internal power supply is insufficient. Extension cable is enclosed.	Power can be supplied to I/O module, intelligent function module, and bus conversion module.  Up to 2 modules can be connected.
5 FX5 intelligent function module	Module with functions other than input/output.	Up to 16 expansion modules including the I/O module can be connected (excluding the extension power supply module).
6 Bus conversion module	Conversion module for connecting FX3 Series expansion module.	FX3 Series expansion module can be connected only to the right side of the bus conversion module.
7 FX5 expansion board	Board connected to front of CPU module to expand functions.	Up to 1 module can be connected to the front of the CPU module. (Expansion adapter can also be used.)
8 FX5 expansion adapter	Adapter connected to left side of CPU module to expand functions.	Up to 6 modules can be connected to the left side of the CPU module.
9 FX3 extension power supply module	Module for expanding power supply if CPU module's internal power supply is insufficient.	The bus conversion module is required for use. Up to 2 modules can be connected.
<b>10</b> FX3 intelligent function module	Module with functions other than input/output.	The bus conversion module is required for use. When using the FX3 extension power supply module, up to 8 modules*can be used. When not using the FX3 extension power supply unit, up to 6 modules*can be used.

<sup>\*:</sup> Excluding some models

### **TOPU** module

		Number of	Power supp	ly capacity		No of input	No of autout
Туре	Function	occupied input/ output points	5 V DC power supply	24 V DC service power supply	I/O type	No. of input points	No. of output points
FX5U-32MR/ES			oints 900 mA 400 mA (480 mA*)	DC input (sink/source)/relay output			
FX5U-32MT/ES		32 points		(480 mA*)	DC input (sink/source)/transistor (sink)	16 points	16 points
FX5U-32MT/ESS					DC input (sink/source)/transistor (source)		
FX5U-64MR/ES	ODII dolo		1100 mA	1100 mA 600 mA (740 mA*)	DC input (sink/source)/relay output	32 points	32 points
FX5U-64MT/ES	CPU module (service power built-in)	64 points			DC input (sink/source)/transistor (sink)		
FX5U-64MT/ESS	(Service power built-iii)				DC input (sink/source)/transistor (source)		
FX5U-80MR/ES				000 4	DC input (sink/source)/relay output		40 points
FX5U-80MT/ES		80 points 1100 mA	1100 mA	600 mA (770 mA*)	DC input (sink/source)/transistor (sink)	40 points	
FX5U-80MT/ESS				(770 IIIA )	DC input (sink/source)/transistor (source)		

 $<sup>\</sup>boldsymbol{*}$  : Power supply capacity when using external power supply for input circuit.

### 2 I/O module

		Number of	Power supply capacity			No. of input	No. of output
Type	Function	occupied input/ output points	5 V DC power supply	24 V DC service power supply	I/O type	points	points
FX5-32ER/ES	Innest/actions to mande da	32 points 965 mA		65 mA 250 mA (310 mA*)	DC input(sink/source)/relay output		16 points
FX5-32ET/ES	Input/output module (service power built-in)		965 mA		DC input (sink/source)/transistor (sink)	16 points	
FX5-32ET/ESS					DC input (sink/source)/transistor (source)		

 $<sup>\</sup>boldsymbol{*}$  : Power supply capacity when using external power supply for input circuit.

### 3 FX5 extension power supply module

		Number of	Power supply capacity		
Туре	Function	occupied input/ output points	5 V DC power supply	24 V DC power supply	
FX5-1PSU-5V	Extension power supply	_	1200 mA*	300 mA*	

<sup>\*:</sup> Refer to the manual if the ambient temperature exceeds 40°C.

### 4 I/O module

Tuna	I/O format	Number of occupied	Current consumption			
Туре	1/O format	input/output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply	
FX5-8EX/ES	DC input (sink/source)	8 points	75 mA	50 mA		
FX5-16EX/ES	DC input (sink/source)	16 points	100 mA	85 mA		
FX5-8EYR/ES	Relay output					
FX5-8EYT/ES	Transistor output (sink)	8 points	75 mA	75 mA		
FX5-8EYT/ESS	Transistor output (source)				_	
FX5-16EYR/ES	Relay output					
FX5-16EYT/ES	Transistor output (sink)	16 points	100 mA	125 mA		
FX5-16EYT/ESS	Transistor output (source)					

### 5 FX5 intelligent function module

	Туре	Function	Number of occupied	Current consumption		
			input/output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
	FX5-40SSC-S	Simple Motion 4-axis control (SSCNET III/H compatible)	8 points	_	_	250 mA

### 6 Bus conversion module

Туре	Function	Number of occupied	Current consumption		
		input/output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
FX5-CNV-BUS	Bus conversion FX5→FX3	8 points	150 mA	_	_

### 7 FX5 Expansion board

Tuna	Function	Number of occupied	Current consumption		
Type		input/output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
FX5-232-BD	RS-232C communication		20 mA		
FX5-485-BD	RS-485 communication				
EVE 422 BD COT	RS-422 communication	_	20 mA*	_	_
FX5-422-BD-GOT	(for GOT connection)				

<sup>\*:</sup> The current consumption will increase when the 5 V type GOT is connected.

### 8 FX5 Expansion adapter

Tune	Firmation	Function Number of occupied		Current consumption		
Type	Function	input/output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply	
FX5-232ADP	RS-232C communication		30 mA	30 mA	_	
FX5-485ADP	RS-485 communication		20 mA			
FX5-4AD-ADP	4 ch voltage input/current input	_	10 mA	20 mA		
FX5-4DA-ADP	4 ch voltage output/current output			_	160 mA	

### 9 FX3 extension power supply module

	Туре	Function	Number of occupied	Current consumption		
			input/output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
	FX3U-1PSU-5V	Extension power supply	_	1000 mA*	300 mA*	_

<sup>\*:</sup> Refer to the manual if the ambient temperature exceeds 40°C.

### 10 FX3 intelligent function module

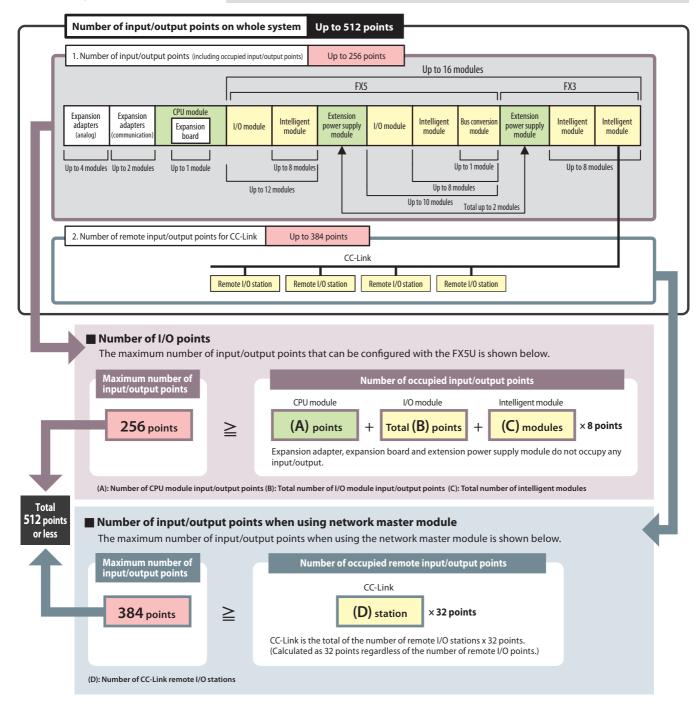
Tuno	Function	Number of occupied	Current consumption			
Type	Function	input/output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply	
FX3U-4AD	4 ch voltage input/current input		110 mA		90 mA	
FX3U-4DA	4 ch voltage output/current output	8 points	120 mA		160 mA	
FX3U-4LC	4-loop temperature control (thermocouple, PT and mini voltage)	o points	160 mA		50 mA	
FX3U-16CCL-M	CC-Link Master (Ver. 2.00 and Ver. 1.10 compatible)	*	_	_	240 mA	
FX3U-64CCL	CC-Link intelligent device station				220 mA	
FX3U-1PG	Pulse output for independent 1-axis control	8 points	150 mA		40 mA	
FX3U-2HC	2 ch high-speed counter		245 mA		_	

<sup>\*:</sup> Varies according to settings.

### **Calculation of current consumed** by expansion modules The power required for the expansion adapter, expansion board and expansion module is supplied from the CPU module or extension power supply module. Use the following calculations to confirm whether the Power fed from CPU module Power fed from powered I/O module Power fed from extension power supply module required power can be supplied. (All calculations must be satisfied.) ■ Power fed from powered I/O module ■ Power fed from extension power supply module ■Power fed from CPU module [5 V DC power supply] [5 V DC power supply] [5 V DC power supply] [24 V DC power supply] [24 V DC power supply] $<\!\!\text{Caution>} \text{ If the calculation results are negative, the power capacity is exceeded so review the system configuration.}$ \*: The 24 V DC service power calculation results value (when positive) indicate the 24 V DC service power supply's remaining capacity, The number of connected modules may be limited for some products. Refer to page 20 for details. and can be used as an external load power.

### **Rules of System Configuration**

The FX5U CPU module can control a total of 512 points including the CPU module and expansion device input/output points and remote input/output points.



### Limitation on number of modules when expanding

The number of connectable modules is limited for the following products. Refer to the manual for details.

Туре	Model/type	Setting method/precautions
	FX3U-4AD	
	FX3U-4DA	■ When using FX3U extension power supply module: Up to 8 modules can be connected per system
	FX3U-1PG	■ When not using FX3U extension power supply module: Up to 6 modules can be connected per system.
Intelligent function module for FX3 Series	FX3U-4LC	
Intelligent function module for 1 X3 Series	FX3U-16CCL-M	Up to 1 module can be connected for the entire system.
	FX3U-64CCL	op to i module can be connected for the entire system.
	FX3U-2HC	Up to 2 modules can be connected for the entire system.
	1 X30-211C	When not using the FX3U-1PSU-5V, connect immediately after the bus conversion module.



# **Selecting the FX5UC Model**

### **■**Product configuration



Туре	Details	Connection details, model selection
1 CPU module	PLC with built-in CPU, power supply, input/output and program memory.	Various expansion devices can be connected.
2 I/O module (connector type)  Connector type product for expanding the input/output.		The input/output can be expanded to up to 256 points.  (Expansion module: Max. 12 modules (excluding connector conversion module)).  The total with CC-Link remote input/output is max. 512 points.
3 Connector conversion module	Converts the connector for connecting the FX5 Series expansion devices.	Expansion devices for the FX5 Series can be connected.
4 I/O module (terminal block type) Product for expanding the input/output.		The input/output can be expanded to up to 256 points. (Expansion module: Max. 12 modules (excluding connector conversion module)). The total with CC-Link remote input/output is max. 512 points.
5 FX5 intelligent function module	Module with functions other than input/output.	Up to 12 expansion modules including the I/O module can be connected (excluding the connector conversion module).
6 Bus conversion module	Conversion module for connecting FX3 Series expansion module.	The FX3 Series expansion module can be connected only to the right side of the bus conversion module.
7 FX5 expansion adapter	Adapter connected to left side of CPU module to expand functions.	Up to 6 modules can be connected to the left side of the CPU module.
8 FX3 intelligent function module	Module with functions other than input/output.	A bus conversion module is required for use.  Up to 6 bus conversion modules* can be connected on the right side.

<sup>\*:</sup> Excluding some models

### 1 CPU module

		Number of	Power supply capacity			No. of input	No. of output
Туре	Function	occupied input/ output points	5 V DC power supply	24 V DC service power supply	I/O type	points	points
FX5UC-32MT/D	CPU module	32 points	720 mA 500 mA		DC input (sink)/transistor (sink)	16 points	16 mainta
FX5UC-32MT/DSS	CFO Module	32 points	720 IIIA	500 IIIA	DC input (sink/source)/transistor (source)	16 points	16 points

### 2 I/O module(connector type)

		Number of occupied input/	Current consumption			
Туре	I/O format	output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply	
FX5-C32EX/D	DC input (sink)					
FX5-C32EX/DS	DC input (sink/source)			_		
FX5-C32EYT/D	Transistor output (sink)	22 mainta	120 mA	200 mA		
FX5-C32EYT/DSS	Transistor output (source)	32 points	120 MA	200 MA	_	
FX5-C32ET/D	DC input (sink)/Transistor output (sink)			100 mA		
FX5-C32ET/DSS	DC input (sink/source)/Transistor output (source)			100 MA		

### 3 Connector conversion module

		Number of occupied input/	Current consumption		
Туре	Function	output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
FX5-CNV-IFC	Connector conversion	_	_	_	_

### 4 I/O module (terminal block type)

		Number of occupied input/	Current consumption		
Туре	Function	output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
FX5-8EX/ES	DC input (sink/source)	8 points	75 mA	50 mA*	
FX5-16EX/ES	DC input (sink/source)	16 points	100 mA	85 mA*	
FX5-8EYR/ES	Relay output				
FX5-8EYT/ES	Transistor output (sink)	8 points	75 mA	75 mA	
FX5-8EYT/ESS	Transistor output (source)				_
FX5-16EYR/ES	Relay output				
FX5-16EYT/ES	Transistor output (sink)	16 points	100 mA	125 mA	
FX5-16EYT/ESS	Transistor output (source)				

<sup>\*:</sup> Since external power supply is used for input circuit in FX5UC CPU module systems, power supply from CPU module is not included.

### 5 FX5 intelligent function module

		Number of accoming input/	Current consumption		
Туре	Function	Number of occupied input/ output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
FX5-40SSC-S	Simple Motion 4-axis control (SSCNET III/H compatible)	8 points	_	_	250 mA

### 6 Bus conversion module

		Number of occupied input/	Current consumption		
Type	Function	output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
FX5-CNV-BUSC	Bus conversion (connector)FX5→FX3	8 points	150 mA		
FX5-CNV-BUS	Bus conversion FX5→FX3	o points	150 MA	_	_

### 7 FX5 Expansion adapter

		Number of occupied input/	Current consumption		
Туре	Function	output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
FX5-232ADP	RS-232C communication		30 mA	- 30 mA	
FX5-485ADP	RS-485 communication		20 mA	30 IIIA	_
FX5-4AD-ADP	4 ch voltage input/current input	_	10 mA	20 mA	
FX5-4DA-ADP	4 ch voltage output/current output		IO IIIA	_	160 mA

### 8 FX3 intelligent function module

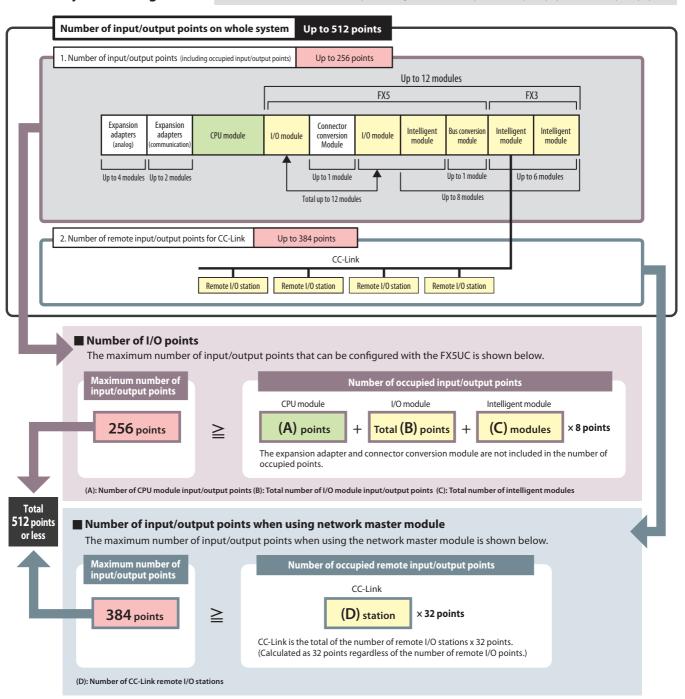
		Number of occupied input/	or of occupied input/ Current consumption		
Туре	Function	output points	5 V DC internal current consumption	24 V DC internal current consumption	24 V DC external electric supply
FX3U-4AD	4 ch voltage input/current input		110 mA		90 mA
FX3U-4DA	4 ch voltage output/current output	8 points	120 mA		160 mA
FX3U-4LC	4-loop temperature control (thermocouple, PT and mini voltage)	o points	160 mA		50 mA
FX3U-16CCL-M	CC-Link Master (Ver. 2.00 and Ver. 1.10 compatible)	*	_	_	240 mA
FX3U-64CCL	CC-Link intelligent device station				220 mA
FX3U-1PG	Pulse output for independent 1-axis control	8 points	150 mA		40 mA
FX3U-2HC	2 ch high-speed counter		245 mA		_

<sup>\*:</sup> Varies according to settings.

# Calculation of current consumed by expansion modules The power required for the expansion adapter and expansion module is supplied from the CPU module. Use the following calculations to confirm whether the required power can be supplied. (All calculations must be satisfied.) Power fed from CPU module [5 V DC power supply opacity (CPU module) [24 V DC power supply] AVDC service power supply] AVDC service power supply opacity (CPU module) [24 V DC power supply] AVDC service power supply] AVDC service power supply opacity (CPU module) [24 V DC power supply opacity (CPU module) Total current consumption (bata of considered) Total current

### **Rules of System Configuration**

The FXSUC CPU module can control a total of 512 points including the CPU module and expansion device input/output points and remote input/output points.



### Limitation on number of modules when expanding

The number of connectable modules is limited for the following products. Refer to the manual for details

The Hamber of Confectable Includes to Infinited for the following products. Fixed to the Hamber of detaile.				
Туре	Model/type	Setting method/precautions		
	FX3U-4AD			
	FX3U-4DA	Lie to 6 modulos con ha connected for the antire queter		
	FX3U-1PG	Up to 6 modules can be connected for the entire system.		
Intelligent function module for FX3 Series	FX3U-4LC			
Intelligent function module for 1 A3 Series	FX3U-16CCL-M	Up to 1 module can be connected for the entire system.		
	FX3U-64CCL	op to a module can be connected for the entire system.		
	FX3U-2HC	Up to 2 modules can be connected for the entire system.		
	FA3U-2FIG	Connect immediately after the bus conversion module.		

Refer to the manual for details on each device.

# **Product specifications**

### **CPU** module specification

### ☐ Generic Specifications

					Specifications	;				
Item		FX5U					FX5UC			
Operating ambient temperature*1	0 to 55°C (32	0 to 55°C (32 to 131°F)*2								
Storage ambient temperature	-25 to 75°C (-1	-25 to 75°C (-13 to 167°F)								
Operating ambient humidity	5 to 95%RH, r	non-condensatio	n							
Storage ambient humidity	5 to 95%RH, r	non-condensatio	n							
		Frequency	Acceleration	Half amplitude	Sweep count	Frequency	Acceleration	Half amplitude	Sweep count	
	Installed on	5 to 8.4 Hz	_	1.75 mm		5 to 8.4 Hz	_	1.75 mm	10 times each in X, Y, Z directions	
Vibration resistance*3*4	DIN rail	8.4 to 150 Hz	4.9 m/s <sup>2</sup>	_	10 times each in X, Y, Z directions	8.4 to 150 Hz	4.9 m/s <sup>2</sup>	_	(80 min in each direction)	
	Direct	5 to 8.4 Hz	_	3.5 mm	(80 min in each direction)					
	installing	8.4 to 150 Hz	9.8 m/s <sup>2</sup>	_		-				
Shock resistance*3	147 m/s <sup>2</sup> , Action	on time: 11 ms, 3	times by half-sir	ne pulse in each o	direction X, Y, and Z					
Grounding	Class D groun	ding (grounding	resistance: 100 !	Ω or less) <comn< td=""><td>non grounding with a heavy elect</td><td>rical system is n</td><td>ot allowed.&gt;*5</td><td></td><td></td></comn<>	non grounding with a heavy elect	rical system is n	ot allowed.>*5			
Working atmosphere	Free from corr	rosive or flamma	ble gas and exce	essive conductive	dust					
Operating altitude*6	0 to 2000 m	0 to 2000 m								
Installation location	Inside a control panel									
Overvoltage category*7	II or less									
Pollution degree*8	2 or less	2 or less								
Equipment class	Class 2									

- \* 1: The simultaneous ON ratio of available PLC inputs or outputs changes with respect to the ambient temperature, refer to manuals of each product.

  \* 2: For details on Intelligent function modules, refer to manuals of each product.

  \* 3: The criterion is shown in IEC61131-2.

  \* 4: When the system has equipment which specification values are lower than above mentioned vibration resistance specification.

- values, the vibration resistance specification of the whole system is corresponding to the lower specification.  $\pm$  5: For grounding, refer to manuals of each product.

- \* 6 : The PLC cannot be used at a pressure higher than the atmospheric pressure to avoid damage.

  \* 7 : This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises. Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for up to the rated voltage of 300 V is 2500 V.

  \* 8 : This indicates the degree to which conductive material is generated in the environment in which the equipment is used. Pollution level 2 is when only non-conductive pollution occurs. Temporary conductivity caused by condensation must be expected occasionally.

### ☐ Power Supply Specifications

	14		Specif	ications	
	Item	FX5U-32M[]	FX5U-64M[]	FX5U-80M[]	FX5UC-32MT/[]
Rated voltage		100 to 240 V AC			24 V DC
Allowable supply volt	age range	85 to 264 V AC			20.4 to 28.8 V DC
Frequency rating		50/60 Hz			_
Allowable instantaneous power failure time		Operation can be continued upon occurrence of instantaneous power failure for 10 ms or less.			Operation can be continued upon occurrence of instantaneous power failure for 5 ms or less.
Power fuse		250 V, 3.15 A Time-lag fuse	250 V, 5 A Time-lag fuse		125 V, 3.15 A Time-lag fuse
Rush current		25 A max. 5 ms or less/100 V AC 50 A max. 5 ms or less/200 V AC	30 A max. 5 ms or less/100 V AC 60 A max. 5 ms or less/200 V AC		30 A max. 0.5 ms or less/24 V DC
Power consumption*	1	30 W	40 W	45 W	8 W
5 V DC power supply	capacity*3	900 mA	1100 mA	1100 mA	720 mA
24 V DC power	Supply capacity when service power supply is used for input circuit of the CPU module	400 mA	600 mA	600 mA	- 500 mA
supply capacity*2*3	Supply capacity when external power supply is used for input circuit of the CPU module	480 mA	740 mA	770 mA	- 500 mA

- \* 1: This item shows value when all 24 V DC service power supplies are used in the maximum configuration connectable to the CPU module. (The current of the input circuit is included.)

  \* 2: When I/O modules are connected, they consume current from the 24 V DC service power. For details on the service power supply, refer to manuals of each product.

  \* 3: Internal power supply in case of FX3UC-32MT/[]

### □ Performance Specifications

	Specifications			
Item	FX5U/FX5UC			
	Stored-program repetitive operation			
	Refresh system (Direct access input/output allowed by specification of direct access input/output [DX, DY])			
Programming language	Ladder diagram (LD), structured text (ST), function block diagram/ladder diagram (FBD/LD)			
Programming extension function	Function block (FB), structured ladder, label programming (local/global)			
Constant scan	0.2 to 2000 ms (can be set in 0.1 ms increments)			
Fixed cycle interrupt	1 to 60000 ms (can be set in 1 ms increments)			
Timer performance specifications	100 ms, 10 ms, 1 ms			
No. of program executions	32			
No. of FB files	16 (Up to 15 for user)			
Execution type	Standby type, initial execution type, scan execution type, event execution type			
Interrupt type	Internal timer interrupt, input interruption, high-speed comparison match interrupt			
LD X0	34 ns			
MOV D0 D1	34 ns			
Program capacity	64 k steps (128 kbytes, flash memory)			
SD memory card	Memory card capacity (SD/SDHC memory card: Max. 4 GB)			
Device/label memory	120 kbytes			
Data memory/standard ROM	5 Mbytes			
rite count	Max. 20000 times			
Device/label memory	1			
Data memory P: No. of program files/FB: No. of FB files	P: 32, FB: 16			
	2 GB: 511*1			
SD memory card	4 GB: 65534*1			
Display data	Year, month, day, hour, minute, second, day of week (leap year automatic detection)			
Precision	-2.96 to +3.74 (TYP.+1.42) s/d (Ambient temperature: 0°C (32°F)) -3.18 to +3.74 (TYP.+1.50) s/d (Ambient temperature: 25°C (77°F)) -13.20 to +2.12 (TYP3.54) s/d (Ambient temperature: 55°C (131°F))			
(1) No. of input/output points	256 points or less			
(2) No. of remote I/O points	384 points or less			
Total No. of points of (1) and (2)	512 points or less			
Retention method	Large-capacity capacitor			
Retention time	10 days (Ambient temperature: 25°C (77°F))			
Data retained	Clock data			
	Programming extension function Constant scan Fixed cycle interrupt Timer performance specifications No. of FB files Execution type Interrupt type LD XO MOV DO D1 Program capacity SD memory card Device/label memory Data memory/standard ROM rite count Device/label memory Data memory P: No. of program files/FB: No. of FB files SD memory card Display data Precision (1) No. of input/output points (2) No. of remote I/O points Total No. of points of (1) and (2) Retention method Retention imme			

<sup>\* 1:</sup> The value listed above indicates the number of files stored in the root folder.

\* 2: Clock data is retained using the power accumulated in a large-capacity capacitor incorporated into the PLC. When voltage of the large-capacity capacitor drops, clock data is no longer accurately retained. The retention period of a fully charged capacitor (electricity is conducted across the PLC for at least 30 minutes) is 10 days (ambient temperature: 25°C (77°F)). How long the capacitor can hold the data depends on the operating ambient temperature. When the operating ambient temperature is high, the holding period is short.



Refer to the manual for details on each device.

### $\square$ Number of device points

	Item		Base		Max. number of points	
	Input relay (X)		8	1024 points	The total annual and V and V and institute the state in the 050 and to	
	Output relay (Y)		8	1024 points	The total number of X and Y assigned to input/output points is up to 256 points	
	Internal relay (M)	Internal relay (M)			vith parameter)*1	
	Latch relay (L)		10	32768 points (can be changed with parameter)*1		
	Link relay (B)		16	32768 points (can be changed w	vith parameter)*1	
	Annunciator (F)		10	32768 points (can be changed w	vith parameter)*1	
	Link special relay (SB)		16	32768 points (can be changed w	vith parameter)*1	
No. of user device points	Step relay (S)		10	4096 points (fixed)		
	Timer system	Timer (T)	10	1024 points (can be changed wit	th parameter)*1	
	Accumulation timer system	Accumulation timer (ST)	10	1024 points (can be changed wit	th parameter)*1	
	Counter system	Counter (C)	10	1024 points (can be changed wit	th parameter)*1	
	Counter system	Long counter (LC)	10	1024 points (can be changed wit	th parameter)*1	
	Data register (D)		10	8000 points (can be changed with parameter)*1		
	Link register (W)		16	32768 points (can be changed w	vith parameter)*1	
	Link special register (SW)	Link special register (SW)		32768 points (can be changed with parameter)*1		
No. of system device points	Special relay (SM)		10	10000 points (fixed)		
ivo. or system device points	Special register (SD)		10	12000 points (fixed)		
Module access device	Intelligent function module dev	ice	10	65536 points (designated by U[]	\G[])	
No. of index register points	Index register (Z)*2		10	24 points		
No. of index register points	Long index register (LZ)*2		10	12 points		
No. of file register points	File register (R)		10	32768 points (can be changed w	vith parameter)*1	
No. of nesting points	Nesting (N)		10	15 points (fixed)		
No. of pointer points	Pointer (P)		10	4096 points		
No. of pointer points	Interrupt pointer (I)		10	178 points (fixed)		
	Decimal constant (K)	Signed	_	16 bits: -32768 to +32767, 32 bit	s: -2147483648 to +2147483647	
	Decimal constant (K)	Unsigned	_	16 bits: 0 to 65535, 32 bits: 0 to	4294967295	
Others	Hexadecimal constant (H)		_	16 bits: 0 to FFFF, 32 bits: 0 to FFFFFFFF		
	Real constant (E)	Single precision	_	E-3.40282347+38 to E-1.17549435-38, 0, E1.17549435-38 to E3.40282347+38		
	Character string	<del></del>	_	Shift-JIS code max. 255 single-l	byte characters (256 including NULL)	

- $\label{eq:capacity} \begin{picture}(2.5)\put(0.5)\put$

### ☐ Input Specifications

### 24 V DC Input (sink/source)

				Specifications			
It	em	FX5U-32M[]	FX5U-64M[]	FX5U-80M[]	FX5UC-32MT/D	FX5UC-32MT/DSS	
o. of input points		16 points	32 points	40 points	16 points		
onnection type		Removable terminal block (M3 scre	ws)		Connector		
put type		Sink/source			Sink	Sink/source	
nput signal voltage		24 V DC +20 %, -15%					
	X000 to X017	5.3 mA/24 V DC			5.3 mA/24 V DC		
nput signal urrent	X020 and subsequent	4.0 mA/24 V DC			_		
	X000 to X017	4.3 kΩ			4.3 kΩ		
put impedance	X020 and subsequent	5.6 kΩ			-		
	X000 to X017	3.5 mA or more			3.5 mA or more		
N input ensitivity current	X020 and subsequent	3.0 mA or more			- J.S HIA GI HIGIE		
FF input sensitivit		1.5 mA or less					
rr input sensitivit	X000 to X005	200 kHz			200 kHz		
put response	X000 to X003	10 kHz	200 kHz		10 kHz		
equency	X010 to X017	—	10 kHz		—		
	X01010 X017		10 KI IZ				
	Waveform	* T1	10 (dia / fall dia a)				
ulse waveform		T1 (pulse width)	T2 (rise/fall time)				
	X000 to X005	T1: 2.5 μs or more, T2: 1.25 μs or less	T1: 2.5 µs or more, T2: 1.25 µs o	rless	T1: 2.5 μs or more, T2: 1.25 μs or less		
	X006 to X007	T1: 50 µs or more, T2: 25 µs or less			T1: 50 µs or more, T2: 25 µs or less		
	X010 to X017	-	T1: 50 µs or more, T2: 25 µs or le	ess	_		
put response time	X000 to X005	ON: 2.5 µs or less, OFF: 2.5 µs or less	ON: 2.5 µs or less, OFF: 2.5 µs o	or less	ON: 2.5 µs or less, OFF: 2.5 µs or less	S	
H/W filter delay)	X006 to X007	ON: 30 µs or less, OFF: 50 µs or less			ON: 30 µs or less, OFF: 50 µs or less		
	X010 to X017	_	ON: 30 µs or less, OFF: 150 µs or		_		
put response time Digital filter setting		None, 10 µs, 50 µs, 0.1 ms, 0.2 ms, When using this product in an enviro					
nput signal format		No-voltage contact input Sink: NPN open collector transistor Source: PNP open collector transist	or		No-voltage contact input NPN open collector transistor	No-voltage contact input Sink: NPN open collector transis Source: PNP open collector tran	
nput circuit insulation	on .	Photo-coupler insulation					
dication of input o	peration	LED is lit when input is on			LED is lit when input is on (DISP sw	ritch: IN)	
		When using service power supply Sink input wiring	Source inpu	t wiring	Sink input wiring	Sink input wiring	
input circuit configu	ration	Fisher N 100 to 240 V AC 100 t	Source input	Fish   N   Side   Sid	Photocoaple COM Proposarce	Photocogler  Photocogler  Property Inspection of the photocogler  Source input wiring  Source input wiring	
		のV S/S Input impedance X	1 = AT	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		COMO Fuse	

### ☐ Output Specifications

### Relay output

Item		Specifications					
Ite	:111	FX5U-32MR/[]	FX5U-64MR/[]	FX5U-80MR/[]			
No. of output points	No. of output points		32 points	40 points			
Connection type		Removable terminal block (M3 s	screws)				
Output type		Relay					
External power supply		30 V DC or less 240 V AC or less ("250 V AC or	less" if not a CE, UL, cUL compli	ant item)			
Max. load		2 A/point The total load current per comm • 4 output points/common termi • 8 output points/common termi		ng value.			
Min. load	Min. load		5 V DC, 2 mA (reference values)				
Open circuit leakage cu	rrent	_					
Response time	OFF→ON	Approx. 10 ms					
Response time	ON→OFF	Approx. 10 ms					
Insulation of circuit		Mechanical insulation					
Indication of output ope	ration	LED is lit when output is on					
Output circuit configuration		Coder suppy  C power suppy  Fuse  Load  AC power suppy  Fuse	oour.				
		A number is entered in the [] of [COM[]].					

### Transistor output

16-				Specifications			
Ite	m	FX5U-32MT/[]	FX5U-64MT/[]	FX5U-80MT/[]	FX5UC-32MT/D	FX5UC-32MT/DSS	
No. of output points		16 points 32 points 40 points			16 points		
Connection type		Removable terminal block (M3	screws)		Connector		
Output type		Transistor/sink output (FX5U-[] Transistor/source output (FX5L			Transistor/sink output	Transistor/source output	
External power supply		5 to 30 V DC					
Max. load		0.5 A/point The total load current per comr • 4 output points/common termi • 8 output points/common termi		Y000 to Y003: 0.3 A/point Y004 and subsequent: 0.1 A/point The total load current per common terminal should be the following value.  • 8 output points/common terminal: 0.8 A or less*			
Open circuit leakage cu	rrent	0.1 mA or less/30 V DC					
Voltage drop when ON	Y000 to Y003	1.0 V or less					
voltage drop when ON	Y004 and subsequent	1.5 V or less					
Response time	Y000 to Y003	2.5 µs or less/10 mA or more (5 to 24 V DC)					
response time	Y004 and subsequent	0.2 ms or less/200 mA or more (24 V DC) 0.2 ms or less/100 mA (24 V DC)					
Insulation of circuit		Photo-coupler insulation					
Indication of output ope	ration	LED is lit when output is on					
Output circuit configuration		Sink output wiring  Load  DC powr suppy Fuse  A number is entered in the [] of A number is entered in the [] with the content of the content					

<sup>\*:</sup> When 2 common terminals are connected outside the CPU module, resistance load is 1.6 A or less.

### ☐ Built-in Analog input

	,	
16.	em	Specifications
10	em	FX5U
Analog input points		2 points (2 channels)
Analog input	Voltage	0 to 10 V DC (input resistance 115.7 kΩ)
Digital output		Unsigned 12-bit binary
I/O characteristics,	Digital output value	0 to 4000
Maximum resolution	Maximum resolution	2.5 mV
Accuracy (Accuracy in respect to maximum digital output value)	Ambient temperature 25 ±5°C (77±41°F)	Within ±0.5% (±20 digit*)
	Ambient temperature 0 to 55°C (32±131°F)	Within ±0.1% (±40 digit*)
Conversion speed		30 µs/channels (data refreshed every operation cycle)
Absolute maximum inp	out	-0.5 V, +15 V
Isolation		No isolation between analog input circuit and PLC circuit. No isolation between input terminals (channels).
Occupied points		0 points (does not pertain to the max. No. of input/ output points of the PLC.)
Terminal block used		European-type terminal block

<sup>\*: &</sup>quot;Digit" refers to digital values.

### ☐ Built-in Analog output

_ Built-in Analog output				
la.		Specifications		
ITE	em	FX5U		
Analog output points		1 points (1 channels)		
Digital input		Unsigned 12-bit binary		
Analog output	Voltage	0 to 10 V DC (external load resistance 2 k to 1 MΩ)		
I/O characteristics,	Digital input value	0 to 4000		
Maximum resolution	Maximum resolution	2.5 mV		
Accuracy	Ambient temperature	Within ±0.5% (±20 digit*)		
(Accuracy in respect	25 ±5°C (77±41°F)	Within 10.3 % (120 digit )		
to maximum analog	Ambient temperature	Within ±0.1% (±40 digit*)		
output value)	0 to 55°C (32±131°F)	**************************************		
Conversion speed		30 µs (data refreshed every operation cycle)		
Isolation		No isolation between analog output circuit and PLC		
Isolation		circuit.		
Occupied points		0 points (does not pertain to the max. No. of input/		
Cooupied points		output points of the PLC.)		
Terminal block used		European-type terminal block		

<sup>\*: &</sup>quot;Digit" refers to digital values.



### ☐ Built-in RS-485 communication

14	Specifications	
Item	FX5U/FX5UC	
Transmission standards	Conforms to RS-485/RS-422 specifications	
Data transmission speed	Max. 115.2 kbps	
Communication method	Full-duplex (FDX) / Half-duplex (HDX)	
Maximum total extension distance	e 50 m (164' 0")	
	MELSOFT connection	
	MELSEC Communication protocol (3C/4C frames)	
	Non-protocol communication	
Protocol type	MODBUS RTU	
	Inverter communication	
	N:N network	
	Predefined protocol support	
Insulation method	Not insulated	
Terminal resistors	Built-in (OPEN/110 Ω/330 Ω)	
Terminal block used	European-type terminal block	

### ☐ Built-in Ethernet communication

Item		Specifications			
	item	FX5U/FX5UC			
Data transmiss	sion speed	100/10 Mbps			
Communicatio	n mode	Full-duplex (FDX) / Half-duplex (HDX)			
Interface		RJ45 connector			
Transmission r	nethod	Base band			
Maximum segment length (The distance between hub and node)		100 m (328' 1")			
Cascade	100BASE-TX	Cascade connection max. 2 stages*1			
connection 10BASE-T		Cascade connection max. 4 stages*1			
		MELSOFT connection			
Drotocal tuno		SLMP (3E frame)			
Protocol type		Socket communication			
		Predefined protocol support			
Number of sim	ultaneously open connections	Total of 8 for socket communication, MELSOFT connection, SLMP, and Predefined protocol support			
allowed		(Up to 8 external devices can access one CPU module at the same time.)			
Insulation met	nod	Pulse transformer insulation			
Cable used*2	For 100BASE-TX connection	Ethernet standard-compatible cable, category 5 or higher (STP cable)			
Cable used	For 10BASE-T connection	Ethernet standard-compatible cable, category 3 or higher (STP cable)			

<sup>\* 1:</sup> Number of stages that can be connected when a repeater hub is used. When a switching hub is used, check the specifications of the switching hub used. \* 2: A straight cable can be used. If a personal computer or GOT and CPU module are directly connected a cross cable can be used.

### $\square$ Built-in positioning function

======================================					
Item	Specifications				
item	FX5U/FX5UC				
Number of control axes	Independent 4 axes* (Simple linear interpolation by 2-axis simultaneous start)				
Maximum frequency	2147483647 (200 Kpps in pulses)				
Positioning program	Sequence program, Table operation				
Supported CPU units	Transistor output type				
Pulse output	1 instruction (PLSY)				
Positioning	8 instructions (DSZR, DVIT, TBL, PLSV, DRVI, DRVA, DRVTBL, DRVMUL) pulse output				

 $<sup>\</sup>boldsymbol{*}$  : The number of control axes is 2 when the pulse output mode is CW/CCW mode.

### ☐ Built-in high speed counter function

Item	Specifications				
Item	FX5U/FX5UC				
	Input specifications	Maximum frequency			
	1 phase, 1 input counter (S/W)	200 KHz			
	1 phase, 1 input counter (H/W)	200 KHz			
Types of high-speed counters	1 phase, 2 input counter	200 KHz			
	2 phase, 2 input counter [1 edge count]	200 KHz			
	2 phase, 2 input counter [2 edge count]	100 KHz			
	2 phase, 2 input counter [4 edge count]	50 KHz			
Input allocation	Parameter setup*				
High-speed counter instruction	[High-speed processing instruction]  • Setting 32-bit data comparison  • Reset 32-bit data comparison  • Comparison of 32-bit data band  • Start/stop of the 16-bit data high-speed I/O function  • Start/stop of the 32-bit data high-speed I/O function  [High-speed current value transfer instruction]  • High-speed current value transfer of 16-bit data  • High-speed current value transfer of 32-bit data				

<sup>\*:</sup> Refer to manuals of each product.

### **Expansion Device Specifications**

### ☐ I/O Modules

### Powered input/output modules

Model	Total No.		No. of input/output points & Input/output type			
Wodei	of points	Input		Output		type
FX5-32ER/ES			041470		Relay	
FX5-32ET/ES	32 points	16 points	24 V DC (Sink/source)	16 points	Transistor (sink)	Terminal block
FX5-32ET/ESS	]		(SITIK/SOUFCE)		Transistor (source)	

### Input modules

Model	Total No.		of input/output po	oints & Inpu	t/output type Output	Connection type
			Input		Output	type
FX5-8EX/ES	8 points	8 points	24 V DC			Terminal block
FX5-16EX/ES	16 points	16 points	(Sink/source)	_	_	Terrilliai block
FX5-C32EX/D			24 V DC			
FA5-C32EA/D	20:-4-	20:-4-	(sink)			Connector
FX5-C32EX/DS	32 points	32 points	24 V DC (Sink/source)	—	-	
FX5-C32EX/D5						

### **Output modules**

Model	Total No.	No. o	of input/output points & Input/output type			Connection
Wodei	of points		Input	Output		type
FX5-8EYR/ES					Relay	
FX5-8EYT/ES	8 points	_		8 points	Transistor (sink)	Terminal block
FX5-8EYT/ESS					Transistor (source)	
FX5-16EYR/ES				-		Relay
FX5-16EYT/ES	16 points			16 points	Transistor (sink)	
FX5-16EYT/ESS	]				Transistor (source)	
FX5-C32EYT/D	22 nainta			32 points	Transistor (sink)	Connector
FX5-C32EYT/DSS	32 points	-	_  -	32 points	Transistor (source)	Connector

### Input/output modules

Model	Total No.	No. o	No. of input/output points & Input/output type				
Wodei	of points	Input		Output		type	
FX5-C32ET/D	22 paints	16 points	24 V DC (sink)	16 points	Transistor (sink)	Connector	
FX5-C32ET/DSS	32 points 1	sz politis – to politis	24 V DC (source)	10 politis	Transistor (source)	Connector	

### □ Expansion adapters

### FX5-232ADP

Specifications
Conforming to RS-232C/15 m (49' 2")/Photo-coupler isolation (Between communication line and CPU module)
9-pin D-sub, male
Half-duplex/Full-duplex
300/600/1200/2400/4800/9600/19200/38400/57600/115200 (bps)
0 point (no points occupied)
FX5U, FX5UC PLC
5 V DC, 30 mA / 24 V DC, 30 mA

### FX5-485ADP

Item	Specifications
Transmission standard/ Maximum transmission distance/ Insulation	Conforming to RS-485, RS-422/1200 m (3937' 0")/Photo-coupler isolation (Between communication line and CPU module)
Connection method	European terminal block
Communication method	Half-duplex/Full-duplex
Baud rate	300/600/1200/2400/4800/9600/19200/38400/57600/115200 (bps)
Terminal resistor	Built-in (OPEN/110 Ω/330 Ω)
Number of occupied I/O points	0 point (no points occupied)
Applicable CPU module	FX5U, FX5UC PLC
Control power (supplied from CPU module)	5 V DC, 20 mA / 24 V DC, 30 mA

### FX5-4AD-ADP

Item	Specifications					
Number of analog input points	4 points	4 points (4 channels)				
Analog input voltage	-10 to +1	0 V DC (input resista	ance 1 MΩ)			
Analog input current	-20 to +2	20 mA DC (input resi	stance 250 Ω)			
Digital output value	14-bit bi	nary value				
	Analog ir	nput range	Digital output value	Resolution		
		0 to 10 V	0 to 16000	625 µV		
	Valtage	0 to 5 V	0 to 16000	312.5 μV		
Input	Voltage	1 to 5 V	0 to 12800	312.5 µV		
characteristics, resolution*		-10 to +10V	-8000 to +8000	1250 μV		
resolution	Current	0 to 20 mA	0 to 16000	1.25 µA		
		4 to 20 mA	0 to 12800	1.25 µA		
		-20 to +20 mA	-8000 to +8000	2.5 µA		
Accuracy (accuracy for the full scale digital output value)	Ambient temperature 25±5°C: within ±0.1% (±16 digit) Ambient temperature 0 to 55°C: within ±1.0% (±32 digit)					
Absolute maximum input	Voltage: ±15 V, Current: ±30 mA					
Isolation method	Between input terminal and PLC: Photocoupler Between input channels: Non-isolation					
Number of occupied I/O points	0 point (no points occupied)					
Applicable CPU module	EX5U EX5UC PLC					

<sup>\*:</sup> For the input conversion characteristic, refer to manuals of each product.

### FX5-4DA-ADP

Item	Specifications				
Number of analog output points	4 points (4 channels)				
Analog output voltage	-10 to +10 '	V DC (external load	resistance value 1 k to	o 1 MΩ)	
Analog output current	0 to 20 mA	DC (external load r	esistance value 0 to 5	00 Ω)	
Digital input	14-bit bina	ry value			
	Analog out	put range	Digital value	Resolution	
		0 to 10 V	0 to 16000	625 μV	
0	Voltage	0 to 5 V	0 to 16000	312.5 μV	
Output characteristics, resolution*		1 to 5 V	0 to 16000	250 μV	
resolution		-10 to +10V	-8000 to +8000	1250 μV	
	Current	0 to 20 mA	0 to 16000	1.25 μΑ	
	Current	4 to 20 mA	0 to 16000	1 μΑ	
Accuracy (accuracy for the full scale of the analog output value)	Ambient temperature 25±5°C: ±0.1% (Voltage ±20 mV, Current ±40 μA) Ambient temperature 0 to 55°C: ±0.2% (Voltage ±30 mV, Current ±60 μA)				
Isolation method	Between output terminal and PLC: Photocoupler Between output channels: Non-isolation				
Number of occupied I/O points	0 point (no points occupied)				
Applicable CPU module	FX5U, FX5	SUC PLC			

<sup>\*:</sup> For the output conversion characteristic, refer to manuals of each product.

### ☐ Expansion boards

Item	Specifications					
Item	FX5-232-BD	FX5-485-BD	FX5-422-BD-GOT			
Transmission standard	Conforming to RS-232C	Conforming to RS-485, RS-422	Conforming to RS-422			
Maximum transmission distance	15 m (49' 2")	50 m (164' 0")	According to the specification of the GOT			
Connection method	9-pin D-sub, male	European terminal block	8-pin MINI-DIN, female			
Insulation	Not insulated (Between	communication line and (	CPU module)			
Communication method	Half-duplex/Full-duplex	Half-duplex/Full-duplex*	Half-duplex			
Baud rate	300/600/1200/2400/ 4800/9600/19200/ 38400/57600/115200 (bps)*	300/600/1200/2400/ 4800/9600/19200/ 38400/57600/115200 (bps)*	9600/19200/38400/ 57600/115200 (bps)			
Terminal resistor	_	Built-in (OPEN/110 Ω/330 Ω)	_			

 $oldsymbol{st}$  : The communication method and baud rate vary depending on the type of communication

### ☐ Extension power supply module

### FX5-1PSU-5V

Item		Specifications		
Rated Supply voltage	ge	100 to 240 V AC		
All owable supply voltage range		85 to 264 V AC		
Rated frequency		50/60 Hz		
Accuracy (accuracy for the full scale digital output value		Operation can be continued upon occurrence of instantaneous power failure for 10 ms or less.		
Power fuse		250 V 3.15 A Time-lag Fuse		
In-rush current		25 A Max. 5 ms or less/ 100 V AC 50 A Max. 5 ms or less/ 200 V AC		
Power consumption		20 W Max.		
Output current*	24 V DC	0.3 A (Maximum output current depends on the ambient temperature.)		
	5 V DC	1.2 A (Maximum output current depends on the ambient temperature.)		

<sup>\*:</sup> For the current conversion characteristic, refer to manuals of each product.

### ☐ Bus conversion modules

### $\textbf{FX5-CNV-BUS} \; (\textbf{FX5} \; (\textbf{terminal block}) \rightarrow \textbf{FX3} \; (\textbf{terminal block}) \; \textbf{extension})$

Item	Specifications
Number of occupied I/O points	8 point
Applicable CPU module	FX5U, FX5UC PLC
Control power (supplied from CPU module)	5 V DC, 150 mA

### $\textbf{FX5-CNV-BUSC} \; (\textbf{FX5} \; (\textbf{connector}) \rightarrow \textbf{FX3} \; (\textbf{terminal block}) \; \textbf{extension})$

Item	Specifications
Number of occupied I/O points	8 point
Applicable CPU module	FX5UC PLC
Control power (supplied from CPU module)	5 V DC, 150 mA

### $\hfill\square$ Connector conversion module

### $\textbf{FX5-CNV-IFC} \; (\textbf{FX5} \; (\textbf{connector}) \rightarrow \textbf{FX5} \; (\textbf{terminal block}) \; \textbf{extension})$

( ()							
Item	Specifications						
Number of occupied I/O points	0 point (does not occupy any I/O points)						
Applicable CPU module	FX5U, FX5UC PLC						
Control power (supplied from CPU module)	0 mA (no power consumed)						



### **Simple Motion module specification**

### FX5-40SSC-S

### ☐ Control specification

Operation cycle	Item rol axes	Specifications Up to 4 axes
		1.777 ms
		Linear interpolation (Up to 4 axes),
Interpolation fur	nction	Circular interpolation (2 axes)
		PTP (Point To Point) control, Trajectory control (both linear
Control modes		and arc), Speed control, Speed-position switching control,
		Position-speed switching control, Speed-torque control Trapezoidal acceleration/deceleration, S-curve acceleration
Acceleration/de	celeration process	deceleration
Compensation 1	function	Backlash compensation, Electronic gear, Near pass function
Synchronous	Input axis	Servo input axis, Synchronous encoder axis
control	Output axis	Cam axis (Up to 4 axes)
	Number of registration	Up to 64 (depending on memory capacity, cam resolution
Cam control		and number of coordinates)
	Cam data type	Stroke ratio data type, Coordinate data type
Otl:t	Cam auto-generation	Cam auto-generation for rotary cutter
Control unit		mm, inch, degree, pulse 600 data (positioning data No. 1 to 600)/axis (Can be set
Number of posit	ioning data	with MELSOFT GX Works3 or a sequence program.)
Dardon		Parameters, positioning data, and block start data can be
Backup		saved on flash ROM (battery-less backup)
	Home position return method	Proximity dog method, Count method 1, Count method 2,
Home position		Data set method, Scale home position signal detection metho
return	Fast home position return control	Provided
	Sub functions	Home position return retry, Home position shift  1-axis linear control, 2-axis linear interpolation control,
	Linear control	3-axis linear interpolation control, 4-axis linear interpolation
		control*1 (Composite speed, Reference axis speed)
	Fixed-pitch feed control	1-axis fixed-pitch feed, 2-axis fixed-pitch feed,
		3-axis fixed-pitch feed, 4-axis fixed-pitch feed*1
	2-axis circular interpolation	Sub point designation, center point designation
	Speed control	1-axis speed control, 2-axis speed control*1, 3-axis speed control*1, 4-axis speed control*1
Davidanian	Speed-position switching	3-axis speed control , 4-axis speed control
Positioning control	control	INC mode, ABS mode
001101	Position-speed switching	INC mode
	control	INC Hode
	Current value change	Positioning data, Start No. for a current value changing
	NOP instruction	Provided
	JUMP instruction	Unconditional JUMP, Conditional JUMP
	LOOP, LEND	Provided
	High-level positioning control	Block start, Condition start, Wait start, Simultaneous start, Repeated start
	JOG operation	Provided
	Inching operation	Provided
		Possible to connect 1 module (Incremental),
Manual control	Manual pulse generator	Unit magnification (1 to 10000 times)
Manual control		, ,
Expansion	Speed-torque control	Speed control without positioning loops, Torque control,
Expansion control	Speed-torque control	Speed control without positioning loops, Torque control, Tightening & press-fit control
		Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier
Expansion control Absolute position		Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface,
Expansion control Absolute position	on system	Speed control without positioning loops, Torque control, Tightening & press-fit control  Made compatible by setting a battery to servo amplifier  Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface)
Expansion control Absolute position	on system	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface,
Expansion control Absolute position	on system ncoder interface Internal interface Speed limit function	Speed control without positioning loops, Torque control, Tightening & press-fit control  Made compatible by setting a battery to servo amplifier  Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface)  1 channel (Incremental)
Expansion control Absolute position Synchronous er	on system  acoder interface  Internal interface	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value
Expansion control Absolute position Synchronous er	on system ncoder interface Internal interface Speed limit function	Speed control without positioning loops, Torque control, Tightening & press-fit control  Made compatible by setting a battery to servo amplifier  Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface)  1 channel (Incremental)  Speed limit value, JOG speed limit value  Torque limit value_same setting, torque limit value_individual setting  Valid/Invalid setting
Expansion control Absolute position	on system ncoder interface Internal interface Speed limit function Torque limit function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_individual setting Valid/Invalid setting Movable range check with current feed value,
Expansion control Absolute position Synchronous er	Internal interface Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_individual setting Valid/Invalid setting Movable range check with current feed value, movable range check with machine feed value
Expansion control Absolute position Synchronous er	Internal interface Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_individual setting Valid/Invalid setting Valid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided
Expansion control Absolute position Synchronous er	Internal interface Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function	Speed control without positioning loops, Torque control, Tightening & press-fit control  Made compatible by setting a battery to servo amplifier  Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface)  1 channel (Incremental)  Speed limit value, JOG speed limit value  Torque limit value_same setting, torque limit value_individual setting  Valid/Invalid setting  Movable range check with current feed value, movable range check with machine feed value  Provided
Expansion control Absolute positic Synchronous er Functions that limit control	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Speed change function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_individual setting Valid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided Provided 1 to 300 [%]
Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control	Internal interface Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Speed change function Override function	Speed control without positioning loops, Torque control, Tightening & press-fit control  Made compatible by setting a battery to servo amplifier  Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface)  1 channel (Incremental)  Speed limit value, JOG speed limit value  Torque limit value_same setting, torque limit value_individual setting  Valid/Invalid setting  Movable range check with current feed value, movable range check with machine feed value  Provided
Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control	Internal interface Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Speed change function Override function Acceleration/deceleration	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_individual setting Valid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided Provided 1 to 300 [%]
Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Override function Acceleration/deceleration time change function Torque change function Torque change function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_individual setting Valid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided Provided Provided Provided
Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control details	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Override function Acceleration/deceleration time change function Torque change function Target position change function M-code output function	Speed control without positioning loops, Torque control, Tightening & press-fit control  Made compatible by setting a battery to servo amplifier  Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface)  1 channel (Incremental)  Speed limit value, JOG speed limit value  Torque limit value_same setting, torque limit value_individual setting  Valid/Invalid setting  Movable range check with current feed value, movable range check with machine feed value  Provided  Provided  Provided  Provided  Target position address and speed are changeable  Provided
Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control details  Other	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Override function Acceleration/deceleration time change function Torque change function Target position change function M-code output function Step function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value, same setting, torque limit value_individual setting Valid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided Provided 1 to 300 [%] Provided Target position address and speed are changeable Provided Deceleration unit step, Data No. unit step
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Expansion control Absolute position Synchronous er  Functions that limit control  Functions that change control details  Other functions	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Override function Acceleration/deceleration time change function Torque change function Torque change function M-code output function Step function Skip function Teaching function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_individual setting Valid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided
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Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control details  Other functions  Parameter initia External input s  Amplifier-less o	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Override function Acceleration/deceleration time change function Torque change function Torque change function Step function Step function Step function Teaching function Teaching function Italiation function Teaching function Teaching function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_same setting, Valid/Invalid setting Walid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided Provided Provided Provided Provided Provided Target position address and speed are changeable Provided Deceleration unit step, Data No. unit step Via PLC CPU, Via external command signal Provided Via internal interface, CPU, servo amplifier Provided
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Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control details  Other functions  Parameter initia External input s Amplifier-less o Mark detection	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Override function Override function Torque change function Torque change function Torque change function Target position change function M-code output function Skip function Iteraching function Iteraching function Iteraching function Idization function Ignal setting function function Imperation function Indication function setting Indication function setting	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_same setting, torque limit value_individual setting Walid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided Provided Provided Provided Provided Target position address and speed are changeable Provided Deceleration unit step, Data No. unit step Via PLC CPU, Via external command signal Provided Via internal interface, CPU, servo amplifier Provided Regular mode, Specified Number of Detections mode, Ring Buffer mode Up to 4 points
Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control details  Other functions  Parameter initia External input s Amplifier-less o Mark detection	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Override function Override function Torque change function Torque change function Torque change function Target position change function Marcode output function Step function Teaching function Teaching function Iization function Jignal setting function function function Mark detection signal Mark detection setting Jonitor function Mark detection setting Jonitor function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value_same setting, torque limit value_same setting, Valid/Invalid setting Walid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided Provided Provided Provided Provided Target position address and speed are changeable Provided Deceleration unit step, Data No. unit step Via PLC CPU, Via external command signal Provided Via internal interface, CPU, servo amplifier Provided Regular mode, Specified Number of Detections mode, Ring Buffer mode Up to 4 points 16 settings
Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control details  Other functions  Parameter initia External input s Amplifier-less o Mark detection  Optional data m	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Override function Override function Torque change function Torque change function Torque change function Target position change function Marcode output function Step function Teaching function Teaching function Iization function Jignal setting function function function Mark detection signal Mark detection setting Jonitor function Mark detection setting Jonitor function	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value, same setting, torque limit value, individual setting Walid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided Provided Provided Provided Provided Target position address and speed are changeable Provided Deceleration unit step, Data No. unit step Via PLC CPU, Via external command signal Provided Via internal interface, CPU, servo amplifier Provided Regular mode, Specified Number of Detections mode, Ring Buffer mode Up to 4 points 16 settings 4 points/axis
Expansion control Absolute positic Synchronous er  Functions that limit control  Functions that change control details  Other functions  Parameter initia External input s Amplifier-less o Mark detection  Optional data m	Internal interface Speed limit function Torque limit function Forced stop Software stroke limit function Hardware stroke limit function Override function Override function Torque change function Torque change function Torque change function M-code output function Skep function Teaching function Itaction function Mention Teaching function Teaching function Teaching function Mention Mention Mention Mention Mention Mention Mark detection signal Mark detection setting Mark detection setting Monitor function Cation	Speed control without positioning loops, Torque control, Tightening & press-fit control Made compatible by setting a battery to servo amplifier Up to 4 channels (Total of the internal interface, via PLC CPU interface, and servo amplifier interface) 1 channel (Incremental) Speed limit value, JOG speed limit value Torque limit value _ same setting, torque limit value _ individual setting Walid/Invalid setting Movable range check with current feed value, movable range check with machine feed value Provided Repeated on the sternal command signal Provided Via PLC CPU, Via external command signal Provided Regular mode, Specified Number of Detections mode, Ring Buffer mode Up to 4 points iss

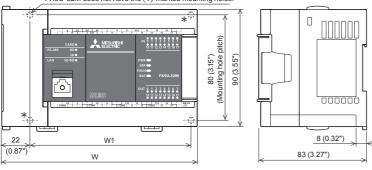
<sup>\* 1:</sup> Only reference axis speed can be specified as the interpolation speed designation method. \* 2: 8 ch word data and 8 ch bit data can be displayed in real time.

### $\hfill\square$ Module specification

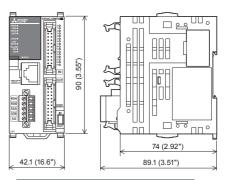
	Item		Specifications				
Servo amplifier co	nnection method		SSCNET III/H				
Maximum overall	cable distance [m	(ft.)]	400 (1312.32)				
Maximum distance	e between station	s [m(ft.)]	100 (328.08)				
Peripheral I/F			Via CPU module (Ethernet)				
Manual pulse gen	erator operation f	unction	Possible to connect 1 module				
			Possible to connect 4 modules				
Synchronous enco	oder operation fur	nction	(Total of the internal interface, via PLC CPU interface, and servo amplifier interface)				
	Number of input	nainta	4 points				
	Number of input	points	Positive common/Negative common shared				
	Input method		(Photocoupler isolation)				
	Rated input volta	age/current	24 V DC/ Approx. 5 mA				
		<u>-</u>	19.2 to 26.4 V DC				
	Operating voltage	ge range	(24 V DC +10%/-20%, ripple ratio 5% or less)				
Input signals (DI)	ON voltage/curr	ent	17.5 V DC or more/ 3.5 mA or more				
	OFF voltage/cur	rent	7 V DC or less/ 1.0 mA or less				
	Input resistance		Approx. 6.8 kΩ				
	Response time		1 ms or less (OFF→ON, ON→OFF)				
	Recommended	wiro cizo	AWG24 ~ 30 (0.2 ~ 0.05 mm <sup>2</sup> )				
	Recommended	WIIE SIZE	* AWG24 (0.2 mm <sup>2</sup> ) recommended				
	Number of input	points	1 point				
	Input method		Positive common/Negative common shared (Photocoupler isolation)				
	Rated input volta	age/current	24 V DC/ Approx. 5 mA				
	Operating voltage	no rango	19.2 to 26.4 V DC				
Forced stop input	Operating voitag	ge range	(24 V DC +10%/-20%, ripple ratio 5% or less)				
signal (EMI)	ON voltage/curr		17.5 V DC or more/ 3.5 mA or more				
	OFF voltage/cur		7 V DC or less/ 1.0 mA or less				
	Input resistance		Approx. 6.8 kΩ				
	Response time		4 ms or less (OFF→ON, ON→OFF)				
	Recommended	wire size	AWG24 ~ 30 (0.2 ~ 0.05 mm <sup>2</sup> ) * AWG24 (0.2 mm <sup>2</sup> ) recommended				
Signal input form			Phase A/Phase B (magnification by 4/magnificatio by 2/magnification by 1), PULSE/SIGN				
		Input pulse	Up to 1 Mpulse/s				
		frequency	(After magnification by 4, up to 4 Mpulse/s)				
		Pulse width	1 μs or more				
	Differential	Leading edge/ trailing edge time	0.25 µs or less				
	output type	Phase difference	0.25 µs or more				
	(26LS31 or equivalent)	Rated input voltage	5.5 V DC or less				
	equivalent)	High voltage	2.0 to 5.25 V DC				
Manual pulse		Low voltage	0 to 0.8 V DC				
generator/		Differential voltage	±0.2 V				
Incremental		Cable length	Up to 30 m (98.43 ft.)				
synchronous		Input pulse	Up to 200 kpulse/s				
encoder signal		frequency	(After magnification by 4, up to 800 kpulse/s)				
		Pulse width	5 μs or more				
	Voltage output	Leading edge/ trailing edge time	1.2 µs or less				
	Open-collector	Phase difference	1.2 µs or more				
	type (5 V DC)	Rated input voltage	5.5 V DC or less				
		High voltage	3.0 to 5.25 V DC				
		Low voltage	0 to 1.0 V DC				
		Cable length	Up to 10m (32.81 ft.)				
Number of occupi	ed I/O points	gu	8 points				
24 V DC internal c	<u> </u>	on	0.25 A				

### **CPU Modules**

- 2-\(\phi4.5\)-diam mounting holes (FX5U-32M) 4-\(\phi4.5\)-diam mounting holes (FX5U-64M, FX5U-80M) FX5U-32M does not have the (\*\*)-marked mounting holes



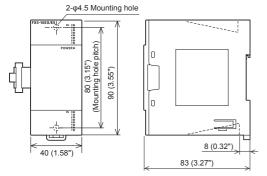
Model name	W: mm (inches)	W1: mm (inches) Mounting hole pitches	MASS (Weight): kg (lbs)
FX5U-32M[]	150 (5.91")	123 (4.85")	Approx. 0.65 (1.43")
FX5U-64M[]	220 (8.67")	193 (7.60")	Approx. 1.0 (2.20")
FX5U-80M[]	285 (11.23")	258 (10.16")	Approx. 1.2 (2.64")



Model name	MASS (Weight): kg (lbs)
FX5UC-32M[]	Approx. 0.2 (0.44")

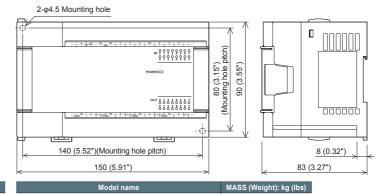
### I/O Modules

### FX5 input module/output module (terminal block type)



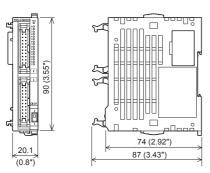
Model name	MASS (Weight): kg (lbs)
FX5-8EX/ES, FX5-8EYR/ES, FX5-8EYT/ES, FX5-8EYT/ESS	Approx. 0.2 (0.44")
EY5.16EY/ES EY5.16EVD/ES EY5.16EVT/ES EY5.16EVT/ESS	Approx 0.25 (0.551")

### FX5 Powered I/O Modules



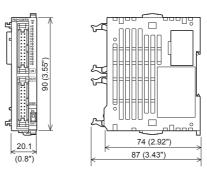
Model name	MASS (Weight): kg (lbs)
FX5-32ER/ES, FX5-32ET/ES, FX5-32ET/ESS	Approx. 0.65 (1.43")

### FX5 input module/output module (connector type)



Model name	MASS (Weight): kg (lbs)
FX5-C32EX/D, FX5-C32EX/DS	Approx 0.45 (0.33")
FX5-C32EYT/D, FX5-C32EYT/DSS	Approx. 0.15 (0.33")

### FX5 I/O module (connector type)

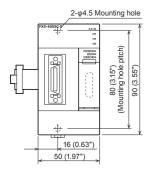


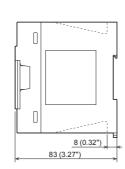
Model name	MASS (Weight): kg (lbs)
FX5-C32ET/D, FX5-C32ET/DSS	Approx. 0.15 (0.33")

### Intelligent Function Module

### FX5-40SSC-S

MASS (Weight): Approx. 0.3 kg (0.66 lbs)





Unit: mm (inches)

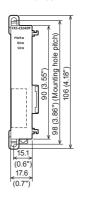
### **Expansion adapters**

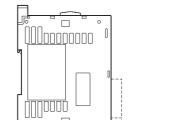
FX5-4AD-ADP / FX5-4DA-ADP

MASS (Weight): Approx. 0.1 kg (0.22 lbs)

JUUo<u>oo</u>oooo 7 (0.28") 15.1

FX5-232ADP / FX5-485ADP





7 (0.28") 74 (2.92"

MASS (Weight): Approx. 0.08 kg (0.18 lbs)

### **Expansion boards**

**FX5-232-BD** MASS (Weight): Approx. 0.02 kg (0.05 lbs)

15.1 (0.6") 17.6

90 (3.55") 98 (3.86") (Mounting hole pitch) 106 (4.18")

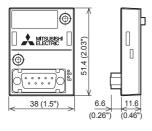
**FX5-485-BD** MASS (Weight): Approx. 0.02 kg (0.05 lbs)

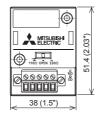
**FX5-422-BD-GOT** MASS (Weight): Approx. 0.02 kg (0.05 lbs)

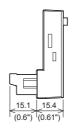
FX5-232ADP

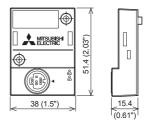
FX5-485ADP 15.1 (0.6")

8.8 (0.35")





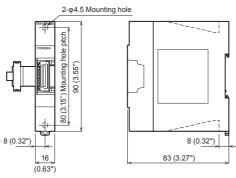




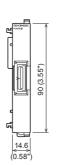
### Bus conversion modules

FX5-CNV-BUS

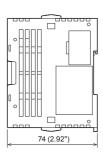
MASS (Weight): Approx. 0.1 kg (0.22 lbs)



FX5-CNV-BUSC

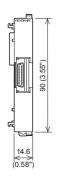


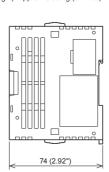
MASS (Weight): Approx. 0.1 kg (0.22 lbs)



FX5-CNV-IFC

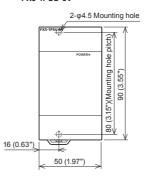
MASS (Weight): Approx. 0.06 kg (0.14 lbs)



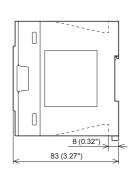


Extension power supply module

FX5-1PSU-5V



MASS (Weight): Approx. 0.3 kg (0.66 lbs)



# **Standards**

### **List of Compatible Products**

Madal Name		E	UL	кс	Ship approvals							
Model Name	EMC	MC LVD CUL		KC	ABS	DNV	LR	GL	BV	RINA	NK	KR
FX5U CPU modul	es											
FX5U-32MR/ES	0	0	0	0	_	_	_	_	_	_	_	_
FX5U-32MT/ES	0	0	0	0	_	_	_	_	_	_	_	_
FX5U-32MT/ESS	0	0	0	0	_	_	_	_	_	_	_	_
FX5U-64MR/ES	0	0	0	0	_	_	_	_	_	_	_	_
FX5U-64MT/ES	0	0	0	0	_	_	_	_	_	_	_	_
FX5U-64MT/ESS	0	0	0	0	_	_	_	_	_	_	_	_
FX5U-80MR/ES	0	0	0	0	_	_	_	_	_	<b>—</b>	_	_
FX5U-80MT/ES	0	0	0	0	_	_	_	_	_	_	_	-
FX5U-80MT/ESS	0	0	0	0	_	_	_	_	_	-	_	_
FX5UC CPU modu	ıles											
FX5UC-32MT/D	0		0	0	I –		_	T —			_	_
FX5UC-32MT/DSS	0		0	0	_	_	_	_	_	_	_	_
FX5 I/O modules (	termin	al bloc	k type)									
FX5-8EX/ES			0	0	T —				<u> </u>		_	_
FX5-16EX/ES	0		0	0	_	_	_	_	_	_	_	_
FX5-8EYR/ES	0	0	0	0	_	_	_	_	_	_	_	_
FX5-8EYT/ES	0		0	0	_	_	_	_	_	_	_	_
FX5-8EYT/ESS	0		0	0	_	_	_	_	_	_	_	_
X5-16EYR/ES	0	0	0	0	_	_	_	_	_	_	_	_
FX5-16EYT/ES	0		0	0	_	_	_	_	_	_	_	_
FX5-16EYT/ESS	0		0	0	_	_	_	_	_	_	_	_
FX5-32ER/ES	0	0	0	0	_	_	_	_	_	_	_	_
FX5-32ET/ES	0	0	0	0	_	_	_	_	_	_	_	_
FX5-32ET/ESS	0	Ō	0	Ō	_	_	_	_	_	T —	_	_
FX5 I/O modules	(conne	ctor ty	pe)									
FX5-C32EX/D	10			0				_			_	_
FX5-C32EX/DS	0		0	0	_	_	_	_	_	_	_	_
FX5-C32EYT/D	0		0	Ō	_	_	_	_	_	<b>—</b>	_	_
X5-C32EYT/DSS	0		Ō	Ō	_	_	_	_	_	<b>—</b>	_	_
X5-C32ET/D	10		Ō	Ō	_	_	_	_	_	<b>—</b>	_	_
FX5-C32ET/DSS	0		0	0	_	_	_	_	_	1_	_	

Madal Nama	C	E	UL	кс			S	hip ap	prova	ls		
Model Name	EMC	LVD	cUL	KC.	ABS	DNV	LR	GL	BV	RINA	NK	KR
◆ FX5 Intelligent fun	ction r	nodule	)									
FX5-40SSC-S	0		0	0	_	_	_	_	_	-	_	
♦ FX5 Extension pov	ver su	oply m	odule									
FX5-1PSU-5V	0	0	0	0	_	_	_	_	_	_	_	_
♦ FX5 Bus conversion	♦ FX5 Bus conversion modules											
FX5-CNV-BUS	0		0	0	_	_	_	_	_	-	_	
FX5-CNV-BUSC	0		0	0	_	_	_	_	_	-	_	_
♦ FX5 Connector co	nversi	on mod	dule									
FX5-CNV-IFC	0		0	0	_	_	_	_	_	_	_	_
♦ FX5 Expansion ad	apters											
FX5-4AD-ADP	0		0	0	_	_	_	_	_	-	_	
FX5-4DA-ADP	0		*	0	_	_	_	_	_	_	_	
FX5-232ADP	0		0	0	_	_	_	_	_	_	_	_
FX5-485ADP	0		0	0	_	_	_	_	_	_	_	_
♦ FX5U Expansion b	oards											
FX5-232-BD	0		_	0	_	_	_	_	_	_	_	_
FX5-485-BD	0		_	0	_	_	_	_	_	_	_	
FX5-422-BD-GOT	0		_	0	_	_	_	_	_	_	_	_
◆ FX3 Intelligent fun	ction r	nodule	S									
FX3U-4AD	0		0	0	_	_	_	_	_	_	_	_
FX3U-4DA	0		0	0	_	_	_	_	_	_	_	_
FX3U-4LC	0		0	0	_	_	_	_	_	_	_	
FX3U-1PG	0		0	0	_	_	_	_	_	_	_	_
FX3U-2HC	0		0	0	_	_	_	_	_	_	_	_
FX3U-16CCL-M	0		0	0	_	_	_	_	_		_	_
FX3U-64CCL	0		0	0	_	_	_	_	_	_	_	_
♦ FX3 Extension pov	ver su	ply m	odule									
FX3U-1PSU-5V	0	0	0	0	_	_	_	_	_	-	_	_

<sup>○:</sup> Compliant with standards or self-declaration □: No need to comply \*: Support planned

### ■EN Standards: Compliance with EC Directives/CE ■UL/cUL Standards marking

EC Directives were issued by the European Council of Ministers to unify standards in the EU Community, and to ensure smooth distribution of products for which safety is ensured. Approximately 20 types of EC Directives for product safety have been issued. Attachment of a CE mark (CE marking) is mandatory on specific products before they may be distributed in the EU. The EMC Directive (Electromagnetic Compatibility Directive) and LVD Directive (Low Voltage Directive) apply to the programmable controller, which is labeled as an electrical part of a machine product under the EC Directives.

### 1) EMC Directive

The EMC Directive is a directive that requires products to have "Capacity to prevent output of obstructive noise that adversely affects external devices: Emission damage" and "Capacity to not malfunction due to obstructive noise from external source: Immunity".

### 2) LVD Directive (Low Voltage Directive)

The LVD Directive is enforced to distribute safe products that will not harm or damage people, objects or assets, etc. With the programmable controller, this means a product that does not pose a risk of electric shock, fire or injury, etc.



UL is the United State's main private safety testing and certification agency for ensuring public safety.

UL sets the safety standards for a variety of fields. Strict reviews and testing are performed following the standards set forth by UL. Only products which pass these tests are allowed to carry the UL Mark.

As opposed to the EN Standards, the UL Standards do not have a legally binding effect. However, they are broadly used as the U.S. safety standards, and are an essential condition for selling products into the U.S..

UL is recognized as a certifying and testing agency by the Canadian Standards Association (CSA). Products evaluated and certified by UL in accordance with Canadian standards are permitted to carry the cUL Mark.





# **Products list**

### CPU & I/O modules

Model	Specification				
Model	Power Supply		Input		Output
CPU modules					
FX5U-32MR/ES	-	16 points		16 points	Relay
FX5U-32MT/ES					Transistor/sink
FX5U-32MT/ESS	1				Transistor/source
FX5U-64MR/ES	1		24 V DC Sink/source		Relay
FX5U-64MT/ES	100 to 240 V AC 50/60 Hz	32 points		32 points	Transistor/sink
FX5U-64MT/ESS	30/00112				Transistor/source
FX5U-80MR/ES	1			40 points	Relay
FX5U-80MT/ES	1	40 points			Transistor/sink
FX5U-80MT/ESS	1				Transistor/source
FX5UC-32MT/D	24.1/.00	40	24 V DC Sink	40 :- t-	Transistor/sink
FX5UC-32MT/DSS	24 V DC	16 points	24 V DC Sink/source	16 points	Transistor/source
I/O modules					
FX5-8EX/ES		8 points	24 V DC Sink/source		
FX5-16EX/ES	1	16 points	24 V DC Silik/source	_	-
FX5-8EYR/ES	1			8 points	Relay
FX5-8EYT/ES	Power supply from CPU module	_	-		Transistor/sink
FX5-8EYT/ESS	Power supply from CPO module				Transistor/source
FX5-16EYR/ES	1			16 points	Relay
FX5-16EYT/ES		_	_		Transistor/sink
FX5-16EYT/ESS	1				Transistor/source
FX5-32ER/ES	400 1 040 1/40	16 points	24 V DC Sink/source	16 points	Relay
FX5-32ET/ES	100 to 240 V AC 50/60 Hz				Transistor/sink
FX5-32ET/ESS					Transistor/source
FX5-C32EX/D		32 points	24 V DC Sink		_
FX5-C32EX/DS	Power supply from CPU module		24 V DC Sink/source	_	_
FX5-C32EYT/D		_		32 points	Transistor/sink
FX5-C32EYT/DSS			_		Transistor/source
FX5-C32ET/D		16 points	24 V DC Sink	16 points	Transistor/sink
FX5-C32ET/DSS			24 V DC Sink/source	10 points	Transistor/source

### **Expansion Boards & Adapters**

Model	Specification
FX5-232-BD	For RS-232C communication
FX5-485-BD	For RS-485 communication
FX5-422-BD-GOT	For GOT RS-422 communication
FX5-232ADP	For RS-232C communication
FX5-485ADP	For RS-485 communication
FX5-4AD-ADP	4 ch analog input adapter
FX5-4DA-ADP	4 ch analog output adapter

### Power supply modules & Bus/Connector conversion modules

Model	Specification
FX5-1PSU-5V	Extension power supply module
FX5-CNV-BUS	Bus conversion FX5(terminal block)→FX3 (terminal block)
FX5-CNV-BUSC	Bus conversion FX5(connector)→FX3 (terminal block)
FX5-CNV-IFC	Connector conversion FX5(connector)→FX5 (terminal block)
FX3U-1PSU-5V	FX3U Extension power supply module

### Intelligent function modules

Model	Specification
FX5-40SSC-S	Simple Motion 4-Axis module
FX3U-4AD	4 ch analog input
FX3U-4DA	4 ch analog output
FX3U-4LC	4 ch temperature control
FX3U-1PG	Positioning pulse output 200 kHz
FX3U-2HC	2 ch 200 kHz high-speed counter
FX3U-16CCL-M	Master for CC-Link (compatible with Ver. 2.00)
FX3U-64CCL	Interface for CC-Link (compatible with Ver. 2.00)

### Software

Туре	Model	Specification
MELSOFT iQ Works (DVD-ROM)	SW2DND-IQWK-E	FA engineering software*1
MELSOFT GX Works3 (DVD-ROM)	SW1DND-GXW3-E	PLC engineering software (includes GX Works2, GX Developer)

<sup>\* 1:</sup> Refer to the manual of the software for supported models.

### User's manuals for the applicable modules

User's manuals for the applicable modules			
Manual name <manual number=""></manual>	Description		
MELSEC iQ-F FX5 User's Manual (Startup) <jy997d58201></jy997d58201>	Describes the performance specifications, procedures before operation, and troubleshooting of the CPU module.		
MELSEC iQ-F FX5UC User's Manual (Hardware) <jy997d61401></jy997d61401>	Describes the details on the hardware of the FX5UC CPU module, including input/output specifications, wiring, installation and maintenance.		
MELSEC iQ-F FX5U User's Manual (Hardware) <jy997d55301></jy997d55301>	Describes the details on hardware of the FX5U series CPU module, including input/output specifications, wiring, installation, and maintenance.		
MELSEC iQ-F FX5 User's Manual (Application) <jy997d55401></jy997d55401>	Describes basic knowledge required for program design, functions of the CPU module, devices/labels, and parameters.		
MELSEC iQ-F FX5 Programming Manual (Program Design) <jy997d55701></jy997d55701>	Describes specifications of ladder, ST, and other programs and of labels.		
MELSEC iQ-F FX5 Programming Manual (Instructions, Standard Functions/Function Blocks) <jy997d55801></jy997d55801>	Describes specifications of instructions and functions that can be used in programs.		
MELSEC iQ-F FX5 User's Manual (Serial Communication) <jy997d55901></jy997d55901>	Describes inverter communication, and non-protocol communication.		
MELSEC iQ-F FX5 User's Manual (SLMP) <jy997d56001></jy997d56001>	Describes SLMP communication.		
MELSEC iQ-F FX5 User's Manual (MELSEC Communication Protocol) <jy997d60801></jy997d60801>	Describes MC protocol.		
MELSEC iQ-F FX5 User's Manual (MODBUS Communication) <jy997d56101></jy997d56101>	Describes MODBUS serial communication.		
MELSEC iQ-F FX5 User's Manual (Ethernet Communication) <jy997d56201></jy997d56201>	Describes the functions of the built-in Ethernet port communication function.		
MELSEC iQ-F FX5 User's Manual (Positioning Control) <jy997d56301></jy997d56301>	Describes the built-in positioning function.		
MELSEC iQ-F FX5 User's Manual (Analog Control) <jy997d60501></jy997d60501>	Describes the analog function.		

### About this product catalog

Due to the constantly growing product range and new or changed product features, the information in this catalog may be updated without notice. Please contact your Mitsubishi Electric product provider for more details. Texts, figures and diagrams shown in this product catalog are intended exclusively for explanation and assistance in planning and ordering the FX5 programmable logic controllers (PLCs) and the associated accessories. Only the manuals supplied with the units are relevant for installation, commissioning and handling of the units and the accessories. The information given in the manuals must be read before installation and commissioning of the units or software.

If any questions arise regarding the application or use of the PLC units and accessories described in this catalog, please contact your Mitsubishi Electric product provider.

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